Closing Internal Timing Channels by Code Transformation

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Work-in-progress!

FOSAD'06

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- Those kind of programs are called non-interferent!

How can a program reveal information to the attacker?

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then $l := 1$;
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if
$$h > 10$$
 $h > 10 \rightsquigarrow l = 1$
then $l := 1$; $h \le 10 \rightsquigarrow l = 0$
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- Motivating example: mobile devices (Geo-localization)

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c_1: if h then skip; skip else skip; l:=1
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 c_2 : skip; skip; l := 0

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 - $h < 0 \implies l = 0$ (l := 1, then l := 0)
- The low race is affected by the secret! (how?)

Internal Timing leak: Magnified

```
p := 0;
while n \geq 0 do
  k := 2^{n-1};
  fork(skip; skip; l := 0);
  if h \geq k then skip; skip else skip;
  l := 1;
  if l = 1 then h := h - k; p := p + k
            else skip;
  n := n - 1
```

Internal Timing Leak: Transformation

Low Code

if ...

High Code

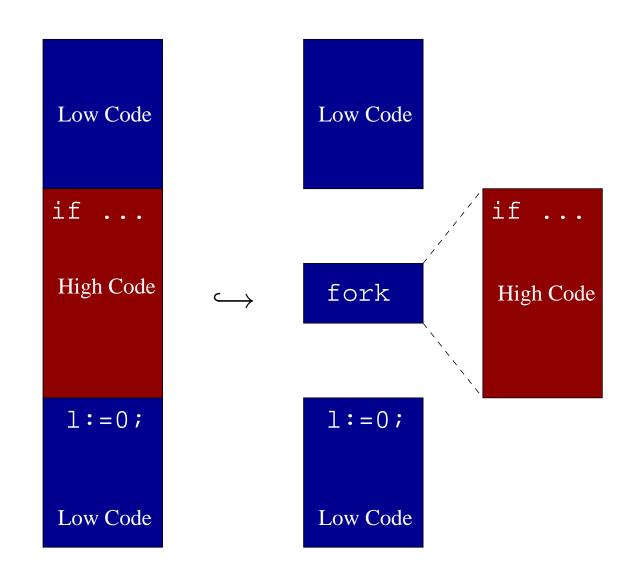
1 := 0;

Low Code

Internal Timing Leak: Transformation

Low Code if ... High Code 1 := 0;Low Code

Internal Timing Leak: Transformation



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Spawn high computations in dedicated threads

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c_1: 	ext{ fork(if } h 	ext{ then skip; skip else skip); } \ l:=1 \ \| c_2: 	ext{ skip; skip; } l:=0
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- Spawn high computations in dedicated threads
 - Good news: no internal timing leaks!

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- Spawn high computations in dedicated threads
 - Good news: no internal timing leaks!
 - Bad news: it may introduce new races between variables!

$$\{h_2=0,l=0\}$$
 (if h_1 then $h_2:=2*h_2+l;$ skip else skip); $l:=1\parallel c_2$

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• Final value of $h_2 \in \{0, 1\}$

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• Final value of $h_2 \in \{0,1\}$ (why?)

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- Take snapshots of low variables when fork

$$\{h_2=0,l=0\}$$
 (if h_1 then $h_2:=2*h_2+l;$ skip else skip); $l:=1\parallel c_2$

• Final value of $h_2 = 0$

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	extsf{fork}((\lambda \hat{l}.	extsf{if}\ h_1\ 	extsf{then}\ h_2:=2*h_2+\hat{l}; 	extsf{skip}\ 	extsf{else}\ 	extsf{skip})@l); l:=1
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- Take snapshots of low variables when fork

$$\{h_2=0,l=0\}$$

$$(ext{if }h_1 ext{ then }h_2:=2*h_2+l; ext{skip else skip}); l:=1;$$
 $h_2:=h_2+1; l:=3 \ \parallel c_2$

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\begin{split} w := \text{newSem}(1); s := \text{newSem}(0); \\ \text{fork}((\lambda \hat{w} \hat{s} \hat{l}. \text{P}(\hat{w}); \text{if } h_1 \text{ then } h_2 := 2*h_2 + \hat{l}; \text{skip else skip}; \textbf{V}(\hat{s}))@wsl); \\ w := s; \ l := 1; \\ \text{fork}((\lambda \quad \hat{l}. \qquad h_2 := h_2 + 1; \qquad)@ \quad l); \\ l := 3 \quad \parallel c_2 \end{split}
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• Final value of $h_2 \in \{1, 2\}$ (why?) (solution?)

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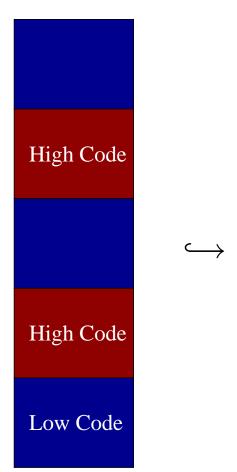
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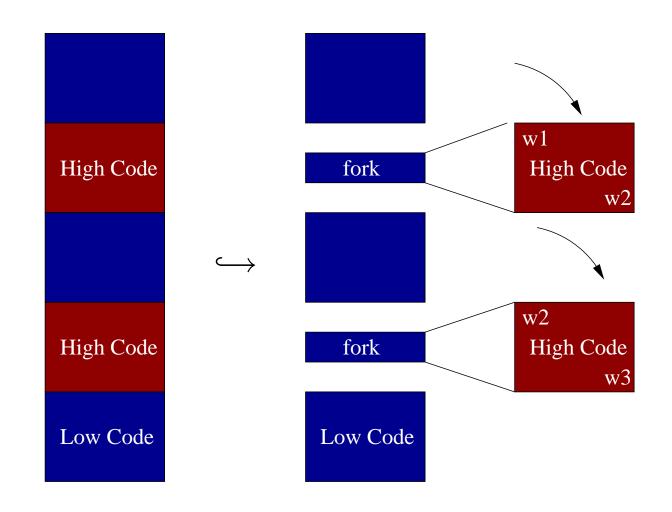
- Final value of $h_2 \in \{1,2\}$ (why?) (solution?)
- Synchronize the spawned dedicated threads

High Code

High Code

Low Code





Results... but technically

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- **Security**: If $\Gamma \vdash c \hookrightarrow_t c'$ then c' is secure under round-robin scheduling.
- **Refinement**: Suppose $\Gamma \vdash c \hookrightarrow_t c'$ and g'_1 and g'_2 are global memories for c' such that $(c', g'_1) \Downarrow g'_2$ using the nondeterministic scheduler ND. Let g_1 and g_2 be the restrictions of g'_1 and g'_2 to the globals of c. Then $(c, g_1) \Downarrow g_2$ using ND.

To sum up...

- Transformation that closes internal timing channels
- Dynamic thread creation in the source language
- No need to change the environment (schedulers, etc)
- Transformation only reject programs with illegal flows inherent to sequential computations