

STOCHASTIC CHEMICAL KINETICS

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A Chemically Reacting System consists of ...

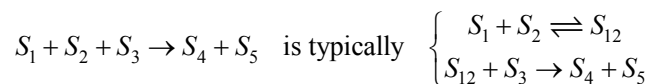
- Molecules of N **chemical species** S_1, \dots, S_N .
 - Inside a volume Ω , at some temperature T .
- M “elemental” **reaction channels** R_1, \dots, R_M .
 - We assume R_j to be a **single instantaneous physical event** that changes the population of at least one species.
 - In practice, “elemental” means that R_j must be one of two types:

Unimolecular: $S_i \rightarrow$ something else,

or

Bimolecular: $S_i + S_j \rightarrow$ something else.

- All other types of reaction (trimolecular, reversible, etc.) are made up of a series of two or more elemental reactions. E.g.:



Question: How does a spatially homogeneous (or well-stirred) chemically reacting system evolve in time?

The Trad Answer:

According to the *reaction rate equation* (RRE).

- A set of coupled, first-order ODEs.
- Derived using ad hoc, phenomenological reasoning.
 - Is *more* than the “mass action equations” of thermodynamics, which apply *only* to systems in complete equilibrium.
- Implies the system evolves *continuously* and *deterministically*.
 - Yet molecules come in *integer numbers* and react *stochastically*.
- Is empirically accurate for large (test tube size) systems
- But is sometimes not adequate for very small (cell-size) systems.

* * *

Doing it “right”: Molecular Dynamics

- The most exact way of describing the system’s evolution.
- The “motion picture” approach: *Tracks the position and velocity of every molecule in the system.*
- Simulates *every* collision, *non-reactive* as well as *reactive*.
- Shows changes in species populations and their spatial distributions.
- **But** . . . it’s *unfeasibly slow* for nearly all realistic systems.

A **great simplification occurs** *if* successive *reactive* collisions tend to be separated in time by *very many non-reactive* collisions.

- The overall effect of the non-reactive collisions is to *randomize*
 - the *velocities* of the molecules (Maxwell-Boltzmann distribution).
 - the *positions* of the molecules (spatially uniform or **well-stirred**),
- Then, instead of having to describe the system's state as the *position, velocity and species of each molecule*, we need only give

$$\mathbf{X}(t) \triangleq (X_1(t), \dots, X_N(t)),$$

$X_i(t) \triangleq$ the *number* of S_i molecules at time t .

But this ***well-stirred simplification***, which . . .

- *ignores* the non-reactive collisions,
- *drastically truncates* the definition of the system's state,
... comes at a price:

$\mathbf{X}(t)$ ***must now be viewed as a stochastic process.***

- But in fact, ***the system was never deterministic to begin with.***
Even if molecules moved according to classical mechanics . . .
 - Unimolecular reactions always involve randomness (QM).
 - Bimolecular reactions usually do too.
 - A system of many colliding molecules is so *sensitive to initial conditions* that, for all practical purposes, it evolves “randomly”.
 - **The system is not isolated.** It's in a *heat bath*, which keeps it “at temperature T ” – via essentially random interactions.

For well-stirred systems, each R_j is completely characterized by ...

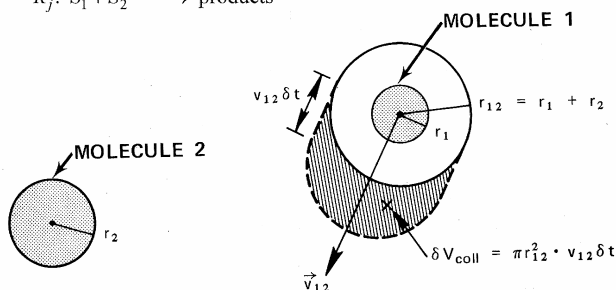
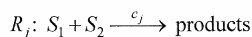
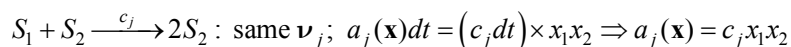
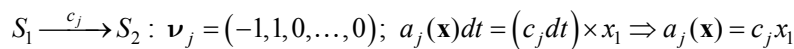
- a **propensity function** $a_j(\mathbf{x})$: Given the system is in state \mathbf{x} , $a_j(\mathbf{x}) dt \triangleq$ **probability** that one R_j event will occur in the next dt .
- The existence and form of $a_j(\mathbf{x})$ follow from *molecular physics*.

- a **state change vector** $\nu_j \equiv (\nu_{1j}, \dots, \nu_{Nj})$:

$\nu_{ij} \triangleq$ the **change** in X_i caused by one R_j event.

- R_j induces $\mathbf{x} \rightarrow \mathbf{x} + \nu_j$. $\{\nu_{ij}\} \equiv$ the “stoichiometric matrix.”

Examples:



$$\text{Prob}\{\text{collision in } dt\} = \frac{(\pi r_{12}^2)(\bar{v}_{12} dt)}{\Omega}. \quad \text{Prob}\{R_j | \text{collision}\} \equiv p_j.$$

$$a_j(\mathbf{x}) dt \equiv \underbrace{\left(\frac{(\pi r_{12}^2)(\bar{v}_{12} dt)}{\Omega} \right)}_{\text{Prob that a typical } S_1-S_2 \text{ pair reacts in next } dt} \times p_j \times x_1 x_2 = \underbrace{\left(\frac{\pi r_{12}^2 \bar{v}_{12} p_j}{\Omega} \right)}_{c_j} x_1 x_2 dt = \underbrace{c_j x_1 x_2}_{a_j(\mathbf{x})} dt$$

$$R_j \text{ iff "collisional K.E." } > E_j \Rightarrow p_j = \exp\left(-\frac{E_j}{k_B T}\right) \dots \text{Arrhenius!}$$

Diffusional motion (well-stirred): $\pi r_{12}^2 \bar{v}_{12}$ is replaced by $4\pi r_{12}(D_1 + D_2)$

Two exact, rigorously derivable consequences . . .

➤ **1.** The *chemical master equation* (CME):

$$\frac{\partial P(\mathbf{x}, t | \mathbf{x}_0, t_0)}{\partial t} = \sum_{j=1}^M \left[a_j(\mathbf{x} - \boldsymbol{\nu}_j) P(\mathbf{x} - \boldsymbol{\nu}_j, t | \mathbf{x}_0, t_0) - a_j(\mathbf{x}) P(\mathbf{x}, t | \mathbf{x}_0, t_0) \right].$$

- $P(\mathbf{x}, t | \mathbf{x}_0, t_0) \triangleq \text{Prob}\{\mathbf{X}(t) = \mathbf{x}, \text{ given } \mathbf{X}(t_0) = \mathbf{x}_0\}$ for $t \geq t_0$.
- Follows from the *probability* statement

$$P(\mathbf{x}, t + dt | \mathbf{x}_0, t_0) = P(\mathbf{x}, t | \mathbf{x}_0, t_0) \times \left[1 - \sum_{j=1}^M (a_j(\mathbf{x}) dt) \right] + \sum_{j=1}^M P(\mathbf{x} - \boldsymbol{\nu}_j, t | \mathbf{x}_0, t_0) \times (a_j(\mathbf{x} - \boldsymbol{\nu}_j) dt).$$

- But the CME is usually too hard to solve.

- Averages: $\langle f(\mathbf{X}(t)) \rangle \triangleq \sum_{\mathbf{x}} f(\mathbf{x}) P(\mathbf{x}, t | \mathbf{x}_0, t_0)$.

If we multiply the CME through by \mathbf{x} and then sum over \mathbf{x} , we find

$$\frac{d\langle \mathbf{X}(t) \rangle}{dt} = \sum_{j=1}^M \boldsymbol{\nu}_j \langle a_j(\mathbf{X}(t)) \rangle.$$

- *If there were no fluctuations,*

$$\langle a_j(\mathbf{X}(t)) \rangle = a_j(\langle \mathbf{X}(t) \rangle) = a_j(\mathbf{X}(t)),$$

and the above would reduce to:

$$\frac{d\mathbf{X}(t)}{dt} = \sum_{j=1}^M \boldsymbol{\nu}_j a_j(\mathbf{X}(t)).$$

- This is the **reaction-rate equation (RRE)**.
- It's usually written in terms of the *concentration* $\mathbf{Z}(t) \triangleq \mathbf{X}(t)/\Omega$.

- **But as yet, we have no justification for ignoring fluctuations.**

➤ **2.** The *stochastic simulation algorithm* (SSA):

A procedure for constructing *sample paths* or *realizations* of $\mathbf{X}(t)$.

Idea: Generate *properly distributed random numbers* for

- the **time** τ to the *next* reaction,
- the **index** j of that reaction.

- $p(\tau, j | \mathbf{x}, t) d\tau \triangleq$ probability, given $\mathbf{X}(t) = \mathbf{x}$, that the *next* reaction will occur in $[t+\tau, t+\tau+d\tau)$, and will be R_j .
 $= P_0(\tau) \times a_j(\mathbf{x}) d\tau$, $P_0(\tau) \triangleq \Pr(\text{no reactions in time } \tau)$.

$$P_0(\tau + d\tau) = P_0(\tau) \times (1 - a_0(\mathbf{x}) d\tau), \text{ where } a_0(\mathbf{x}) \triangleq \sum_{j=1}^M a_j(\mathbf{x}).$$

$$\text{Implies } \frac{dP_0(\tau)}{d\tau} = -a_0(\mathbf{x})P_0(\tau). \quad \text{Solution: } P_0(\tau) = e^{-a_0(\mathbf{x})\tau}.$$

$$\therefore p(\tau, j | \mathbf{x}, t) = e^{-a_0(\mathbf{x})\tau} a_j(\mathbf{x}) = a_0(\mathbf{x}) e^{-a_0(\mathbf{x})\tau} \times \frac{a_j(\mathbf{x})}{a_0(\mathbf{x})}.$$

Thus,

- τ is an *exponential random variable* with mean $1/a_0(\mathbf{x})$,
- j is an *integer random variable* with probabilities $a_j(\mathbf{x})/a_0(\mathbf{x})$.

The "Direct" Version of the SSA

1. In state \mathbf{x} at time t , evaluate $a_1(\mathbf{x}), \dots, a_M(\mathbf{x})$, and $a_0(\mathbf{x}) \equiv \sum_{j'=1}^M a_{j'}(\mathbf{x})$.
2. Draw two unit-interval uniform random numbers r_1 and r_2 , and compute τ and j according to
 - $\tau = \frac{1}{a_0(\mathbf{x})} \ln\left(\frac{1}{r_1}\right)$,
 - $j =$ the *smallest integer* satisfying $\sum_{k=1}^j a_k(\mathbf{x}) > r_2 a_0(\mathbf{x})$.
3. Replace $t \leftarrow t + \tau$ and $\mathbf{x} \leftarrow \mathbf{x} + \nu_j$.
4. Record (\mathbf{x}, t) . Return to Step 1, or else end the simulation.

A Simple Example: $S_1 \xrightarrow{c_1} 0$.

$$a_1(x_1) = c_1 x_1, \quad \nu_1 = -1. \quad \text{Take } X_1(0) = x_1^0.$$

RRE: $\frac{dX_1(t)}{dt} = -c_1 X_1(t)$. Solution is $X_1(t) = x_1^0 e^{-c_1 t}$.

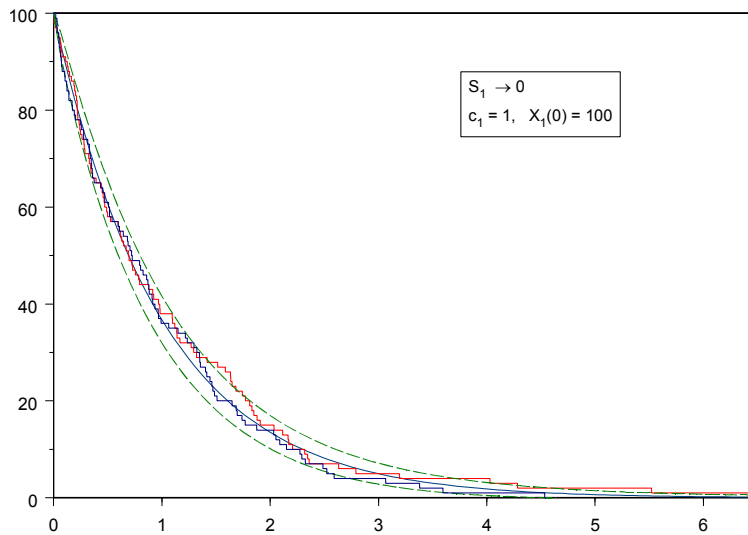
CME: $\frac{\partial P(x_1, t | x_1^0, 0)}{\partial t} = c_1 \left[(x_1 + 1)P(x_1 + 1, t | x_1^0, 0) - x_1 P(x_1, t | x_1^0, 0) \right]$.

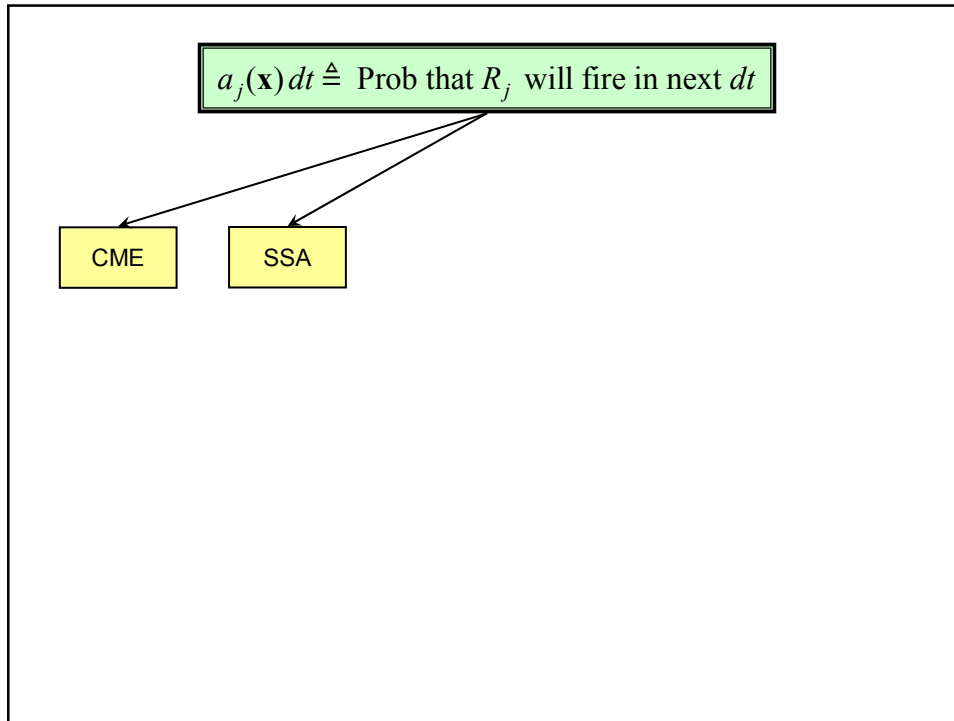
Solution: $P(x_1, t | x_1^0, 0) = \frac{x_1^0!}{x_1! (x_1^0 - x_1)!} e^{-c_1 x_1 t} (1 - e^{-c_1 t})^{x_1^0 - x_1}$ ($x_1 = 0, 1, \dots, x_1^0$)

which implies $\langle X_1(t) \rangle = x_1^0 e^{-c_1 t}$, $\text{sdev}\{X_1(t)\} = \sqrt{x_1^0 e^{-c_1 t} (1 - e^{-c_1 t})}$.

SSA: Given $X_1(t) = x_1$, generate $\tau = \frac{1}{c_1 x_1} \ln\left(\frac{1}{r}\right)$, then update:

$$t \leftarrow t + \tau, \quad x_1 \leftarrow x_1 - 1.$$





The SSA ...

- Is **exact**. It does *not* entail approximating “ dt ” by “ Δt ”.
- Is **procedurally simple**, even when the CME is intractable.
- Comes in a variety of implementations ...
 - Direct Method (Gillespie, 1976)
 - First Reaction Method (Gillespie, 1976)
 - Next Reaction Method (Gibson & Bruck, 2000)
 - First Family Method (Lok, 2003)
 - Modified Direct Method (Cao, Li & Petzold, 2004)
 - Sorting Direct Method (McCollum, et al. 2006)
- **Remains too slow for most practical problems**: Simulating *every* reaction event *one* at a time just takes too much time if any reactants are present in very large numbers.

**We would be willing to sacrifice a little exactness . . .
. . . if that would buy us a faster simulation.**

Tau-Leaping

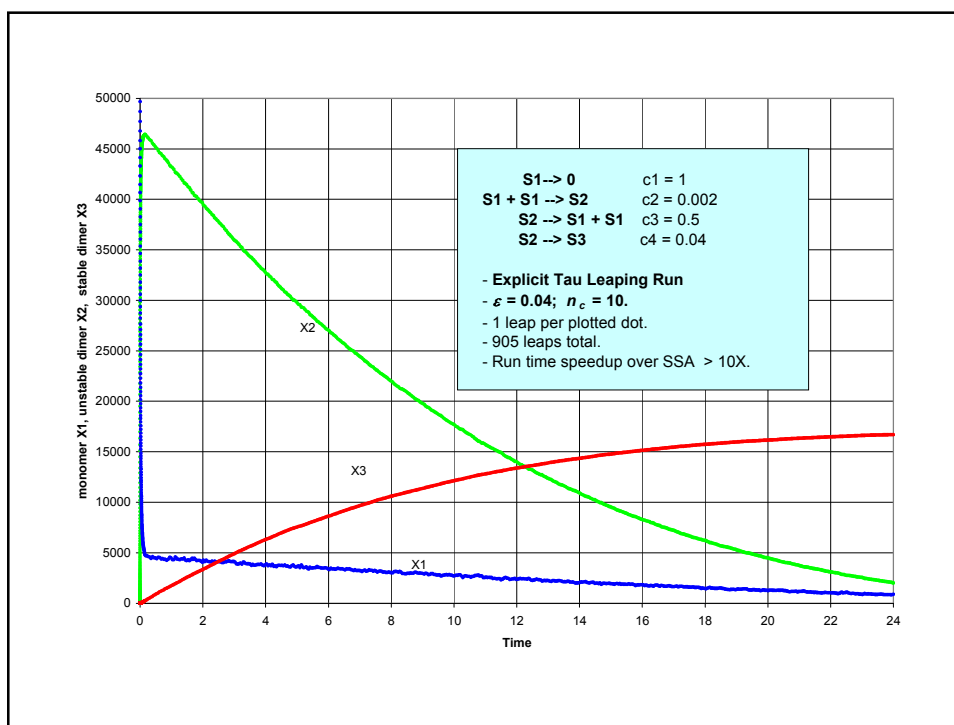
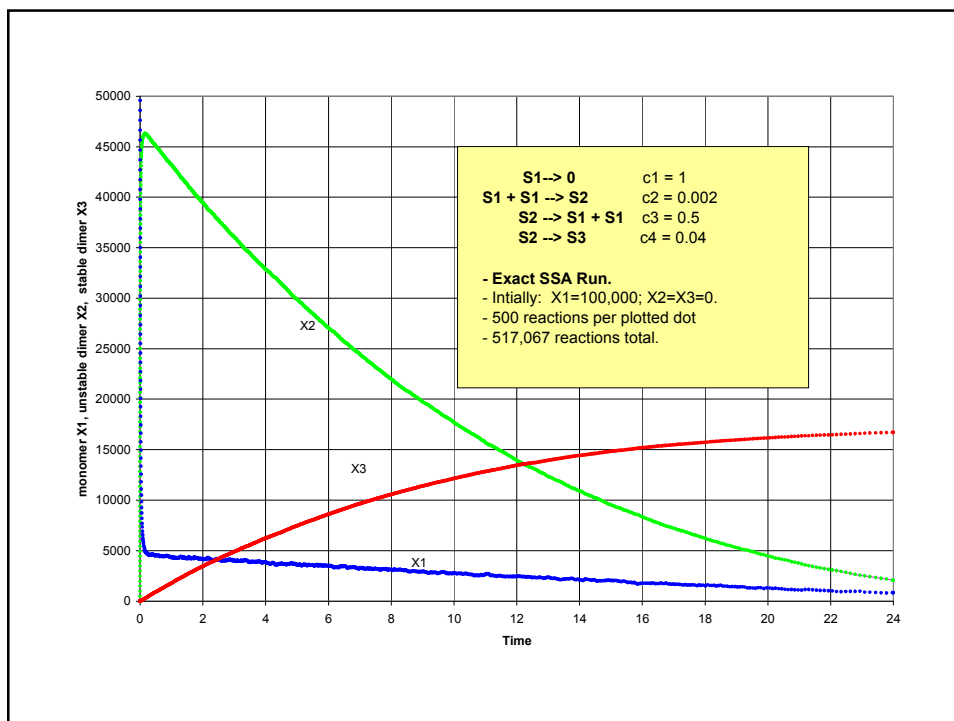
- *Approximately* advances the process by a *pre-selected* time τ , which may encompass *more than one* reaction event.
- *Key*: The “Poisson random variable with mean $a\tau$ ” can be defined:
 $\mathcal{P}(a\tau) \equiv$ the **number of events** that will occur in a time τ , when the probability of an event in any dt is adt , provided a is a positive **constant**.
- With $\mathbf{X}(t) = \mathbf{x}$, let us choose τ *small enough* to satisfy the
Leap Condition: Each $a_j(\mathbf{x}) \approx$ **constant** in $[t, t+\tau]$.
- Then the number of R_j firings in $[t, t+\tau]$ will be $\approx \mathcal{P}(a_j(\mathbf{x})\tau)$. So ...

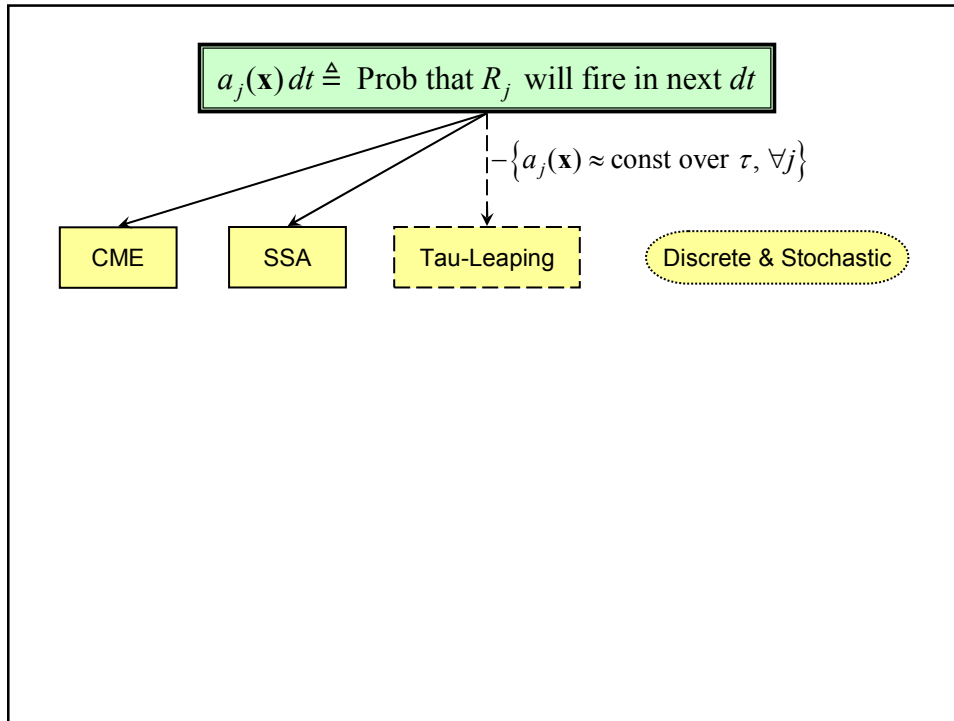
$$\mathbf{X}(t+\tau) \doteq \mathbf{x} + \sum_{j=1}^M \mathcal{P}_j(a_j(\mathbf{x})\tau) \nu_j$$

$$\mathbf{X}(t+\tau) \doteq \mathbf{x} + \sum_{j=1}^M \mathcal{P}_j(a_j(\mathbf{x})\tau) \nu_j$$

- Practical Considerations for Implementing Tau-Leaping -

- **Finding the largest τ that satisfies the Leap Condition.**
 - Accomplished via an **accuracy control parameter** ε .
 - We estimate the largest τ for which $|\Delta_\tau a_j / a_j| \leq \varepsilon, \forall j$.
- **Avoiding negative populations, and segueing to the SSA.**
 - Accomplished via a **second control parameter** n_c .
 - We call any reaction that is within n_c firings of exhausting any reactant a **critical** reaction. Then we tau-leap *no farther* than the *next* firing of a critical reaction.
 - **Becomes the SSA when *all* reactions are classified critical.**





Speeding up Tau-Leaping: **The Langevin Equation**

- Two math facts:
 - If $m \gg 1$, then $\mathcal{P}(m) \approx \mathcal{N}(m, m)$.
 - $\mathcal{N}(m, \sigma^2) = m + \sigma \mathcal{N}(0, 1)$.
- So, with $\mathbf{X}(t) = \mathbf{x}$, suppose we can choose τ **small enough** to satisfy the Leap Condition, **yet also large enough that** $a_j(\mathbf{x})\tau \gg 1, \forall j$.

Then ...
$$\begin{aligned} \mathbf{X}(t+\tau) &\doteq \mathbf{x} + \sum_{j=1}^M \mathcal{P}_j(a_j(\mathbf{x})\tau) \mathbf{v}_j \\ &\doteq \mathbf{x} + \sum_{j=1}^M \mathcal{N}_j(a_j(\mathbf{x})\tau, a_j(\mathbf{x})\tau) \mathbf{v}_j \\ &\doteq \mathbf{x} + \sum_{j=1}^M \left[a_j(\mathbf{x})\tau + \sqrt{a_j(\mathbf{x})\tau} \mathcal{N}_j(0, 1) \right] \mathbf{v}_j \\ \diamond \quad \mathbf{X}(t+\tau) &\doteq \mathbf{x} + \sum_{j=1}^M \mathbf{v}_j a_j(\mathbf{x})\tau + \sum_{j=1}^M \mathbf{v}_j \sqrt{a_j(\mathbf{x})} \mathcal{N}_j(0, 1) \sqrt{\tau} . \end{aligned}$$

$$\mathbf{X}(t+\tau) \doteq \mathbf{x} + \sum_{j=1}^M \boldsymbol{\nu}_j a_j(\mathbf{x}) \tau + \sum_{j=1}^M \boldsymbol{\nu}_j \sqrt{a_j(\mathbf{x})} \mathcal{N}_j(0,1) \sqrt{\tau}$$

- This is the **Langevin leaping formula**.
- It's faster than the ordinary tau-leaping formula, because
 - $a_j(\mathbf{x})\tau \gg 1$ means *lots* of reaction events get leapt over in τ ;
 - *normal* random numbers can be generated faster than Poissons.

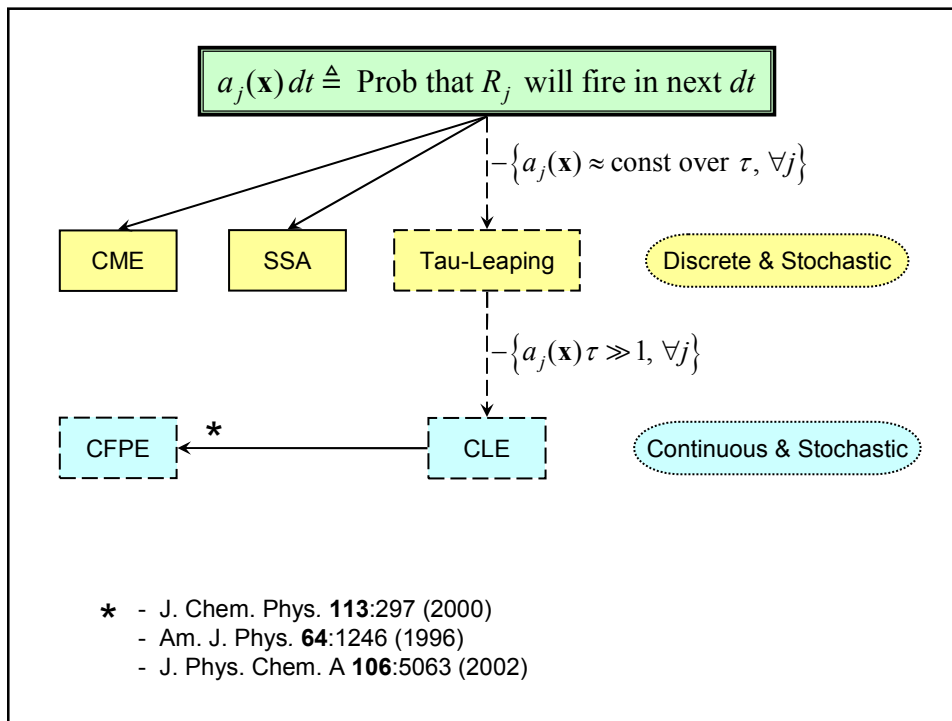
- It directly implies, and is entirely equivalent to, a SDE called the **chemical Langevin equation (CLE)**:

$$\frac{d\mathbf{X}(t)}{dt} \doteq \sum_{j=1}^M \boldsymbol{\nu}_j a_j(\mathbf{X}(t)) + \sum_{j=1}^M \boldsymbol{\nu}_j \sqrt{a_j(\mathbf{X}(t))} \Gamma_j(t) .$$

- Gaussian white noise: $\Gamma(t) \triangleq \lim_{dt \rightarrow 0^+} \frac{\mathcal{N}(0,1)}{\sqrt{dt}} \equiv \lim_{dt \rightarrow 0^+} \mathcal{N}\left(0, \frac{1}{dt}\right)$.

- Satisfies $\langle \Gamma_j(t) \Gamma_{j'}(t') \rangle = \delta_{jj'} \delta(t-t')$.

- Our **discrete stochastic** process $\mathbf{X}(t)$ has now been **approximated** as a **continuous stochastic** process.



The Thermodynamic Limit

Def: All $X_i \rightarrow \infty$, and $\Omega \rightarrow \infty$, with X_i/Ω constants.

- $$\left. \begin{aligned} a_j &= c_j x_1 \sim x_1 \\ a_j &= c_j x_1 x_2 \sim \Omega^{-1} x_1 x_2 \sim x_2 \end{aligned} \right\} \Rightarrow \left\{ \begin{array}{l} \text{In the thermodynamic limit,} \\ \text{all } a_j \text{'s grow like (system size).} \end{array} \right.$$

- So in the thermodynamic limit, we see that in the CLE

$$\frac{d\mathbf{X}(t)}{dt} \doteq \sum_{j=1}^M \mathbf{v}_j a_j(\mathbf{X}(t)) + \sum_{j=1}^M \mathbf{v}_j \sqrt{a_j(\mathbf{X}(t))} \Gamma_j(t) ,$$

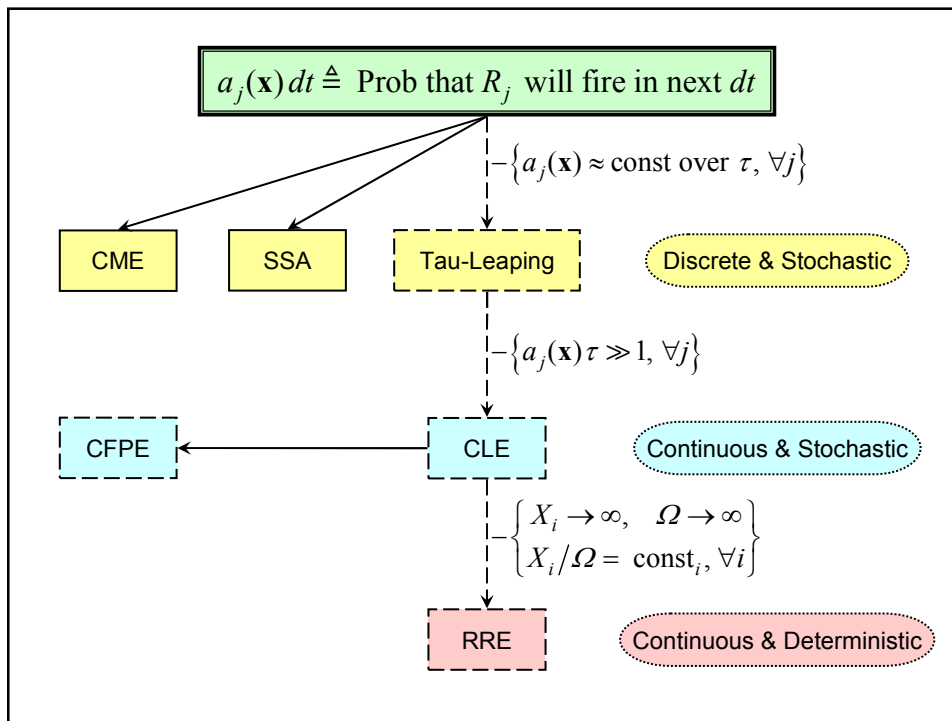
- the *deterministic* term grows like (system size),
- the *stochastic* term grows like (system size)^{1/2}.

- ⇒ Rule of Thumb: *Relative fluctuations die off as (system size)^{-1/2}*.

- At the thermodynamic limit** the stochastic term disappears, leaving

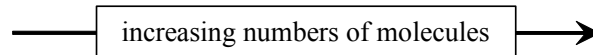
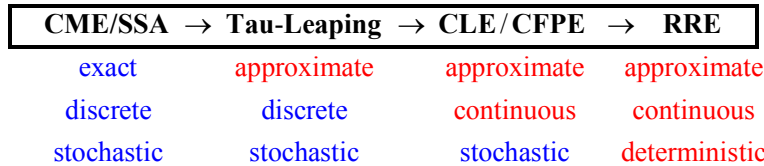
$$\frac{d\mathbf{X}(t)}{dt} \doteq \sum_{j=1}^M \mathbf{v}_j a_j(\mathbf{X}(t)) \quad \dots \text{ the RRE ... derived!}$$

$\mathbf{X}(t)$ has now become a *continuous deterministic* process.



A Spectrum of Descriptive Mathematical Modes
(for **well-stirred** systems)

$$\underbrace{a_j(\mathbf{x}) \approx \text{const}}_{\text{in } [t, t+\tau], \forall j} \quad \underbrace{a_j(\mathbf{x}) \tau \gg 1}_{\forall j} \quad \underbrace{X_i \rightarrow \infty, \Omega \rightarrow \infty}_{X_i/\Omega \rightarrow \text{const}_i}$$



Another Multi-Scale Problem

- Some reactions/species may be *very fast*, others *very slow*.
- “Fast” and “slow” are **interconnected** – not easy to separate.
- Often manifests as *dynamical stiffness*, a known ODE problem.
- SSA still works, and is exact. But it’s agonizingly slow.
- Tau-leaping remains accurate, but the Leap Condition restricts τ to the shortest (fastest) time scale of the system. So even it’s too slow.
- **One approach:** *Implicit Tau-Leaping*
 - A stochastic adaptation of the *implicit Euler method* for ODEs.
- **Another approach:** The *Slow-Scale Stochastic Simulation Algorithm*
 - Skips over the fast reactions and *simulates only the slow reactions*, using specially modified propensity functions. An adaptation of the “rapid equilibrium” / “quasi steady-state” methods for RREs.