# A further application of FASE: study liveness properties on Mutual Exclusion Algorithms

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# Faster Asynchronous Systems Evaluation

FASE (Faster Asynchronous Systems Evaluation):

- Aimed to analyse systems specified in PAFAS algebra
- Different modules loosely-coupled written in Java
- Evaluates the efficiency of a process in the worst-case behaviour
- Checks the presence of catastrophic cycles



F. Buti, M. Callisto De Donato, F. Corradini, M. R. Di Berardini and W. Vogler.

Evaluating the Efficiency of Asynchronous Systems with FASE. In pre-proc. of the 1st Int. Workshop on Quantitative Formal Methods, pp.101-106, Technische Universiteit Eindhoven, 2009

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Apply FASE to study new properties about systems:



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- Aimed to analyse systems specified in PAFAS algebra
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Apply FASE to study new properties about systems:

- Checks liveness properties
- Under the assumption of fairness of actions
- And a process algebra with Non-Blocking Reading
- By studying the presence of catastrophic cycles



F. Buti, M. Callisto De Donato, F. Corradini, M. R. Di Berardini and W. Vogler.

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F. Corradini, M.R. Di Berardini, W. Vogler

Time and Fairness in a Process Algebra with Non-Blocking Reading In Proc. of 35th Conference on Current Trends in Theory and Practice of Computer Science (SOFSEM 2009), LNCS 5404: 193 204 (2009).

# Study liveness properties

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Consider a critical resource that must be accessed from concurrent processes in a mutual way. An algorithm is used to regulate the usage of the resource. Different properties can be studied:

- Is the mutual exclusion preserved?
- Is the algorithm live?

# Study liveness properties

#### Liveness

Something good will happen eventually.

Consider a critical resource that must be accessed from concurrent processes in a mutual way. An algorithm is used to regulate the usage of the resource. Different properties can be studied:

- Is the mutual exclusion preserved?
- Is the algorithm live?

#### Liveness

Whenever, at some point, a process  $P_i$  requests the execution of its critical section, then at some later point it will enter it.

The verification of liveness properties usually requires some fairness assumption.



#### D.J. Walker

Automated Analysis of Mutual Exclusion algorithms using CCS Formal Aspects of Computing 1, pp. 273-292, 1989

# A characterization of fair sequences

(Weak) fairness of actions: each action continuously enabled along a computation must eventually proceed.

#### Theorem (fair traces)

An infinite trace  $\alpha_0 \alpha_1 \alpha_2 \dots$  is fair iff there exists a non-Zeno timed execution sequence

$$P_0 \xrightarrow{1} \xrightarrow{v_0} P1 \xrightarrow{1} \xrightarrow{v_1} \dots P_n \xrightarrow{1} \xrightarrow{v_n} P_{n+1} \dots$$

where  $v_0 v_1 \ldots v_m \ldots = \alpha_0 \alpha_1 \ldots \alpha_i \ldots$ 



F. Corradini, M.R. Di Berardini, W. Vogler

Fairness of Actions in System Computations Acta Informatica 43, pp. 73 130, 2006.

F. Corradini, M.R. Di Berardini, W. Vogler

Time and Fairness in a Process Algebra with Non-Blocking Reading In Proc. of 35th Conference on Current Trends in Theory and Practice of Computer Science (SOFSEM 2009), LNCS 5404: 193 204 (2009).



. Costa, C. Stirling

Weak and Strong Fairness in CCS Information and Computation 73, pp. 207-244, 1987

#### Liveness in mutual exclusion algorithms

If, whenever at any computation a process  $P_i$  requests the execution of its critical section (e.g. req<sub>i</sub> action), then in any continuation of that computation  $P_i$  will perform its critical section (e.g. cs<sub>i</sub> action).

#### Liveness in mutual exclusion algorithms

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- To establish that an algorithm preserves its liveness property, we check if any occurrence of *req<sub>i</sub>* in a fair trace is eventually followed by *cs<sub>i</sub>*.
- Namely, we check if the process is free from catastrophic cycles.



#### F. Corradini and W. Vogler

Measuring the performance of asynchronous systems with PAFAS Theor. Comput. Sci 335(2-3): 187-213 (2005).



#### F. Corradini, M.R. Di Berardini, W. Vogler

Time and Fairness in a Process Algebra with Non-Blocking Reading. In Proc. of 35th Conference on Current Trends in Theory and Practice of Computer Science (SOFSEM 2009), LNCS 5404: 193 204 (2009).

## Catastrphic cycles

A cycle in the rRTS(P) is called catastrophic if it contains a positive number of time steps but no in's and no out's.



#### Catastrphic cycles and liveness

In a fair trace, after the request  $req_i$  there exists an infinite sequence of actions and time steps without any  $cs_i$  action.



# Dekker algorithm



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```
B1F = b1rf.B1F + b1wf.B1F + b1wt.B1T:
B1T = b1rt.B1T + b1wt.B1T + b1wf.B1F:
B2F = b2rf.B2F + b2wf.B2F + b2wt.B2T:
B2T = b2rt.B2T + b2wt.B2T + b2wf.B2F:
K1 = kr1.K1 + kw1.K1 + kw2.K2;
K2 = kr2.K2 + kw2.K2 + kw1.K1:
PV = (B1F | [] | B2F | [] | K1);
P1 = in.b1wt.P11;
                                         P2 = req2.b2wt.P21;
P11 = b2rf.P14 + b2rt.P12:
                                         P21 = b1rf.P24 + b1rt.P22:
P12 = kr1.P11 + kr2.b1wf.P13:
                                         P22 = kr2.P21 + kr1.b2wf.P23;
P13 = kr1.b1wt.P11 + kr2.P13;
                                         P23 = kr2.b2wt.P21 + kr1.P23:
                                         P24 = exit2.kw1.b2wf.P2;
P14 = out.kw2.b1wf.P1:
DEKKER = ((P1 | [] | P2) | [B] | PV) [L \rightarrow tau];
```

```
B = sort(PV), L = sort(DEKKER) \setminus \{in, out\}
```

Result on Dekker

Dekker is not live meaning that catastrophic cycles are detected.

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• Some unwanted behaviour: a process reading/writing a variable can indefinitely block another process that tries to read/write it.

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Dekker is not live meaning that catastrophic cycles are detected.

- Some unwanted behaviour: a process reading/writing a variable can indefinitely block another process that tries to read/write it.
- Dekker is not live under the assumption of fairness of actions.
- Suffers of Starvation and livelock.



F. Corradini, M.R. Di Berardini, W. Vogler

Checking a Mutex Algorithm in a Process Algebra with Fairness Proc. of CONCUR'06, pp. 142-157, LNCS 4137, 2006 • We could consider the scenario where multiple concurrent processes can read the same variable:

 $B_i(false) = \{b_i rf\} > b_i wf.B_i(false) + b_i wt.B_i(true)$  $B_i(true) = \{b_i rt\} > b_i wt.B_i(true) + b_i wf.B_i(false)$  • We could consider the scenario where multiple concurrent processes can read the same variable:

 $B_i(false) = \{b_i rf\} > b_i wf.B_i(false) + b_i wt.B_i(true)$  $B_i(true) = \{b_i rt\} > b_i wt.B_i(true) + b_i wf.B_i(false)$ 

- Dekker is still not live.
- Catastrophic cycles are detected.
- Livelock is still present.

# Liveness in Dekker - further considerations

- The only ordinary actions are those actions that correspond to the writing of a new value
- These actions can be tought of as non-destructive operations, allowing other potential concurrent accesses
- This way of accessing variables is not new, e.g database systems.

$$B_i(false) = \{b_i rf, b_i wf\} > b_i wt.B_i(true)$$
  
$$B_i(true) = \{b_i rt, b_i wt\} > b_i wf.B_i(false)$$

• Dekker is live and no catastrophic cycle is detected.



F. Corradini, M.R. Di Berardini, W. Vogler

Time and Fairness in a Process Algebra with Non-Blocking Reading. In Proc. of 35th Conference on Current Trends in Theory and Practice of Computer Science (SOFSEM 2009), LNCS 5404: 193 204 (2009).

# Dekker's algorithm

 $B1F = {b1rf, b1wf} > b1wt.B1T;$  $B1T = \{b1rt, b1wt\} > b1wf.B1F;$  $B2F = {b2rf, b2wf} > b2wt.B2T;$  $B2T = \{b2rt, b2wt\} > b2wf.B2F;$  $K1 = \{kr1, kw1\} > kw2.K2;$  $K2 = \{kr2, kw2\} > kw1.K1;$ PV = (B1F | [] | B2F | [] | K1);P1 = req1.b1wt.P11;P2 = req2.b2wt.P21;P11 = b2rf.P14 + b2rt.P12;P21 = b1rf.P24 + b1rt.P22:P12 = kr1.P11 + kr2.b1wf.P13: P22 = kr2.P21 + kr1.b2wf.P23: P13 = kr1.b1wt.P11 + kr2.P13: P23 = kr2.b2wt.P21 + kr1.P23: P24 = exit2.kw1.b2wf.P2;P14 = exit1.kw2.b1wf.P1;

DEKKER = ((P1 |[] | P2) |[B] |PV) [L -> tau];

 $B = sort(PV), L = sort(DEKKER) \setminus \{in, out\}$ 

# Dijkstra's algorithm



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# Dijkstra's algorithm

```
B1F = b1rf.B1F + b1wf.B1F + b1wt.B1T:
                                              B2F = b2rf.B2F + b2wf.B2F + b2wt.B2T:
B1T = b1rt.B1T + b1wt.B1T + b1wf.B1F;
                                              B2T = b2rt.B2T + b2wt.B2T + b2wf.B2F:
                                              C2F = c2rf.C2F + c2wf.C2F + c2wt.C2T:
C1F = c1rf.C1F + c1wf.C1F + c1wt.C1T:
C1T = c1rt.C1T + c1wt.C1T + c1wf.C1F;
                                              C2T = c2rt.C2T + c2wt.C2T + c2wf.C2F;
  K1 = kr1.K1 + kw1.K1 + kw2.K2 + get.(k1r1.put.K1 + k2r1.put.K1);
  K2 = kr2.K2 + kw2.K2 + kw1.K1 + get.(k1r2.put.K2 + k2r2.put.K2);
  PV = (B1T || B2T || C1T || C2T || K1);
P1 = b1wf.in.P11;
                                              P2 = b2wf.req2.P21;
P11 = kr1.P13 + kr2.c1wt.P12:
                                              P21 = kr2.P23 + kr1.c2wt.P22:
P12 = get.(k1r1.(b1rt.put.kw1.P11 +
                                              P22 = get.(k2r2.(b2rt.put.kw2.P21 +
b1rf.put.P11) + k1r2.(b2rt.put.kw1.P11 +
                                              b2rf.put.P21) + k2r1.(b1rt.put.kw2.P21 +
b2rf.put.P11));
                                              b1rf.put.P21)):
P13 = c1wf.(c2rf.P11 + c2rt.P14): P14 =
                                              P23 = c2wf.(c1rf.P21 + c1rt.P24);
out.c1wt.b1wt.P1:
                                               P24 = cs2.c2wt.b2wt.P2:
```

DIJKSTRA = ((P1 |[] | P2) |[B] | PV)[L -> tau];

 $B = sort(PV), L = sort(DIJKSTRA) \setminus \{in, out\}$ 

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```
C10 = c1w0.C10 + c1w1.C11 + c1w2.C12 +
                                               C20 = c2w0.C20 + c2w1.C21 + c2w2.C22 +
c1r0.C10;
                                               c2r0.C20;
C11 = c1w0.C10 + c1w1.C11 + c1w2.C12 +
                                               C21 = c2w0.C20 + c2w1.C21 + c2w2.C22 +
c1r1.C11:
                                               c2r1.C21:
                                               C22 = c2w0.C20 + c2w1.C21 + c2w2.C22 +
C12 = c1w0.C10 + c1w1.C11 + c1w2.C12 +
c1r2.C12:
                                               c2r2.C22:
  K1 = kr1.K1 + kw1.K1 + kw2.K2;
  K2 = kr2.K2 + kw2.K2 + kw1.K1
  PV = (C10 || C20 || K1);
P1 = c1w1.in.P11:
                                               P2 = c2w1.req2.P21;
P11 = kr1.P13 + kr2.P12;
                                               P21 = kr2.P23 + kr1.P22;
P12 = c2r0.P13 + c2r1.P11 + c2r2.P11:
                                               P22 = c1r0.P23 + c1r1.P21 + c1r2.P21;
P13 = c1w2.P14;
                                               P23 = c2w2.P24;
P14 = c2r0.P15 + c2r1.P15 + c2r2.P16;
                                               P24 = c1r0.P25 + c1r1.P25 + c1r2.P26;
P15 = kw1.out.kw2.c1w0.P1;
                                               P25 = kw2.cs2.kw1.c2w0.P2:
P16 = c1w1.P11:
                                               P26 = c2w1.P21;
```

```
KNUTH = ((P1 |[] | P2) |[B] | PV)[L -> tau];
```

 $B = sort(PV), L = sort(KNUTH) \setminus \{in, out\}$ 

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# Peterson's algorithm



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# Peterson's algorithm

```
      B1F = b1rf.B1F + b1wf.B1F + b1wt.B1T;
      B2F = b2rf.B2F + b2wf.B2F + b2wt.B2T;

      B1T = b1rt.B1T + b1wt.B1T + b1wf.B1F;
      B2T = b2rt.B2T + b2wt.B2T + b2wf.B2F;

      K1 = kr1.K1 + kw1.K1 + kw2.K2;
      K2 = kr2.K2 + kw2.K2 + kw1.K1;

      PV = (B1F || B2F || K1);
      P2 = b2wt.req2.kw1.P21;

      P1 = b1wt.in.kw2.P11;
      P2 = b2wt.req2.kw1.P21;

      P1 = b2rf.P12 + b2rt.(kr2.P11 + kr1.P12);
      P2 = b1rf.P22 + b1rt.(kr1.P21 + kr2.P22);

      P1 = out.b1wf.P1;
      P2 = cs2.b2wf.P2;
```

PETERSON = ((P1 |[] | P2) |[B] | PV)[L -> tau];

 $B = sort(PV), L = sort(PETERSON) \setminus \{in, out\}$ 

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# Lamport's algorithm



F. Buti, M. Callisto, F. Corradini, M.R. Di Berardini

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```
      B1F =birf.B1F +biwf.B1F + biwt.B1T;
      B2F =b2rf.B2F +b2wf.B2F + b2wt.B2T;

      B1T=birt.B1T +biwf.B1F + biwt.B1T;
      B2T=b2rt.B2T +b2wf.B2F + b2wt.B2T;

      PV = (B1F | |B2F);
      B2T=b2rt.B2T +b2wf.B2F + b2wt.B2T;

      P1 = biwt.in.P11;
      P2 = b2wt.req2.P21;

      P11 = b2rf.P12+b2rt.P11;
      P21 = b1rf.P23 + b1rt.b2wf.P22;

      P12 = out.b1wf.P1;
      P22 = b1rf.b2wt.P21 + b1rt.P22;

      P23 = cs2.b2wf.P2;
      P23 = cs2.b2wf.P2;
```

```
LAMPORT = ((P1 |[] | P2) |[B] | PV)[L -> tau];
```

```
B = sort(PV), L = sort(LAMPORT) \setminus \{in, out\}
```

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- All the algorithms have been coded in PAFAS and automatically checked by the tool FASE.
- Interesting results have been found:

Algorithm	Walker	Without read acts	With read acts
Dekker	not live	not live	live
Dijkstra	not live	not live	not live
Knuth	live	not live	not live
Peterson	live	not live	live
$Lamport_{live_{p_1} \land live_{p_2}}$	not live	not live	not live
$Lamport_{live_{p_1} \land \neg live_{P_2}}$	live	not live	live

Table: Comparing Walker result with catastrophic cycles detection

### Peterson's algorithm

- Without using read actions, FASE has detected catastrophic cycles: *P<sub>i</sub>* continuously reads the same value from the same variable while *P*<sub>2</sub> is stuck and waits to write it.
- When read acts are used to models the action of read the same value from a variable, Peterson's algorithm becomes live.

### Peterson's algorithm

- Without using read actions, FASE has detected catastrophic cycles: *P<sub>i</sub>* continuously reads the same value from the same variable while *P*<sub>2</sub> is stuck and waits to write it.
- When read acts are used to models the action of read the same value from a variable, Peterson's algorithm becomes live.

#### Lamport's algorithm

- The same considerations about Peterson's algorithms are valid if we consider to observe  $P_1$ .
- If we observe  $P_2$ , than the catastrophic cycles are detected in both cases as expected (due to the asymmetry of the processes).

# Dijkstra's algorithm

- In Dijkstra's algorithm, FASE has detected catastrophic cycles in both cases.
- It is known that this algorithm is susceptible to starvation.
- But there are also catastrophic cycles as following:

# Dijkstra's algorithm

- In Dijkstra's algorithm, FASE has detected catastrophic cycles in both cases.
- It is known that this algorithm is susceptible to starvation.
- But there are also catastrophic cycles as following:

$$\underline{K2} = \{\underline{kr2}, kw2\} > (kw1.K1 + \underline{get}.(k1r2.put.K2 + k2r2.put.K2));$$
  

$$\underline{P12} = \underline{get}.(\ldots);$$

<u>P21</u> =  $\frac{kr2}{P23}$ . P23 + kr1.c2wt.P22;

$$P = \underline{P_{12}} \parallel \underline{P_{22}} \parallel_B \dots K2 \xrightarrow{\tau(get)} \xrightarrow{\tau} \dots \xrightarrow{1} P$$

- FASE has detected catastrophic cycles in both cases.
- When read acts are used, the follow catastrophic cycles is detected:

$$C12 = \{c1r2, c1w2\} > (c1w0.C10 + c1w1.C11);$$

$$P21 = kr2.P23 + kr1.P22$$

$$P22 = c1r0.P23 + c1r1.P21 + c1r2.P21$$

$$P23 = c2v2.P24$$

$$P24 = c1r0.P25 + c1r1.P25 + c1r2.P26$$

$$P24 = c1r0.P25 + c1r1.P25 + c1r2.P26$$

$$P26 = c2w1 P21$$

- FASE has detected catastrophic cycles in both cases.
- When read acts are used, the follow catastrophic cycles is detected:

$$C12 = \{c1r2, c1w2\} > (c1w0.C10 + c1w1.C11);$$

 $C21 = \{c2r1, c2w1\} > (c2w0.C20 + c2w2.C22);$  $C22 = \{c2r2, c2w2\} > (c2w0.C20 + c2w1.C21);$ 

$$P21 = kr2.P23 + kr1.P22$$

$$P22 = c1r0.P23 + c1r1.P21 + c1r2.P21$$

$$P23 = c2w2.P24$$

$$P24 = c1r0.P25 + c1r1.P25 + c1r2.P26$$

$$P26 = c2w1.P21$$

 $P = P14 \parallel P24 \parallel_B (C12 \parallel C22 \parallel K(2)) \xrightarrow{1}{\rightarrow}$ 

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$$P23 = c2w2.P24$$

$$P24 = c1r0.P25 + c1r1.P25 + c1r2.P26$$

$$P26 = c2w1.P21$$

$$P = P14 \parallel P24 \parallel_B (C12 \parallel C22 \parallel K(2)) \xrightarrow{1}$$
  
$$P' = \underline{P14} \parallel \underline{P24} \parallel_B (\underline{C12} \parallel \underline{C22} \parallel K(2)) \xrightarrow{\tau(c2w1)}$$

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- When read acts are used, the follow catastrophic cycles is detected:

$$C12 = \{c1r2, c1w2\} > (c1w0.C10 + c1w1.C11);$$

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$$P24 = c1r0.P25 + c1r1.P25 + c1r2.P26$$

$$P26 = c2w1.P21$$

$$P = P14 \parallel P24 \parallel_B (C12 \parallel C22 \parallel K(2)) \xrightarrow{1}$$

$$P' = \underline{P14} \parallel \underline{P24} \parallel_B (\underline{C12} \parallel \underline{C22} \parallel K(2)) \xrightarrow{\tau(c2w1)}$$

$$P'' = P14 \parallel P21 \parallel_B (C12 \parallel C21 \parallel K(2))$$

- FASE has detected catastrophic cycles in both cases.
- When read acts are used, the follow catastrophic cycles is detected:

$$C12 = \{c1r2, c1w2\} > (c1w0.C10 + c1w1.C11);$$

$$P21 = kr2.P23 + kr1.P22$$

$$P22 = c1r0.P23 + c1r1.P21 + c1r2.P21$$

$$P23 = c2w2.P24$$

$$P24 = c1r0.P25 + c1r1.P25 + c1r2.P26$$

$$P26 = c2w1.P21$$

$$P = P14 \parallel P24 \parallel_B (C12 \parallel C22 \parallel K(2)) \xrightarrow{1} P' = \underline{P14} \parallel \underline{P24} \parallel_B (\underline{C12} \parallel \underline{C22} \parallel K(2)) \xrightarrow{\tau(c2w1)} P'' = P14 \parallel P21 \parallel_B (C12 \parallel C21 \parallel K(2)) \xrightarrow{1} P''$$

- FASE has detected catastrophic cycles in both cases.
- When read acts are used, the follow catastrophic cycles is detected:

$$C12 = \{c1r2, c1w2\} > (c1w0.C10 + c1w1.C11);$$

$$P21 = kr2.P23 + kr1.P22$$

$$P22 = c1r0.P23 + c1r1.P21 + c1r2.P21$$

$$P23 = c2w2.P24$$

$$P24 = c1r0.P25 + c1r1.P25 + c1r2.P26$$

$$P26 = c2w1.P21$$

$$P = P14 \parallel P24 \parallel_B (C12 \parallel C22 \parallel K(2)) \xrightarrow{1} P' = \underline{P14} \parallel \underline{P24} \parallel_B (\underline{C12} \parallel \underline{C22} \parallel K(2)) \xrightarrow{\tau(c2w1)} P'' = P14 \parallel P21 \parallel_B (C12 \parallel C21 \parallel K(2)) \xrightarrow{1} \xrightarrow{\tau(kr2)}$$

- FASE has detected catastrophic cycles in both cases.
- When read acts are used, the follow catastrophic cycles is detected:

$$C12 = \{c1r2, c1w2\} > (c1w0.C10 + c1w1.C11);$$

$$P21 = kr2.P23 + kr1.P22$$

$$P22 = c1r0.P23 + c1r1.P21 + c1r2.P21$$

$$P23 = c2w2.P24$$

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$$P26 = c2w1.P21$$

$$P = P14 \parallel P24 \parallel_B (C12 \parallel C22 \parallel K(2)) \xrightarrow{1}$$

$$P' = \underline{P14} \parallel \underline{P24} \parallel_B (\underline{C12} \parallel \underline{C22} \parallel K(2)) \xrightarrow{\tau(c2w1)}$$

$$P'' = P14 \parallel P21 \parallel_B (C12 \parallel C21 \parallel K(2)) \xrightarrow{1} \xrightarrow{\tau(kr2)} \xrightarrow{\tau(c2w2)} P$$

# Thanks!

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