

Model-Driven Non-Functional Analysis

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*Progetto PRIN PaCo (Performance-aware Computing)
Kickoff Meeting, Bertinoro, 23-24 ottobre 2008*

SUMMARY

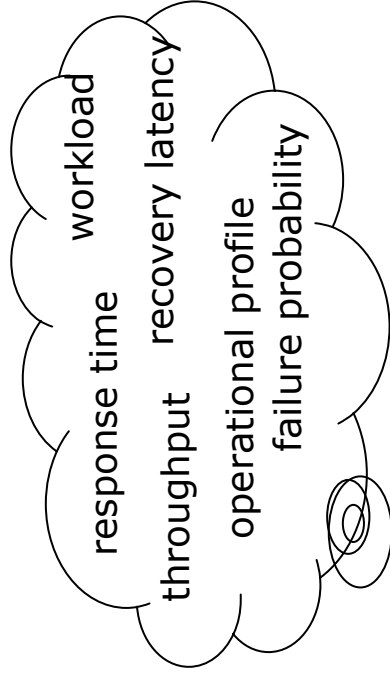
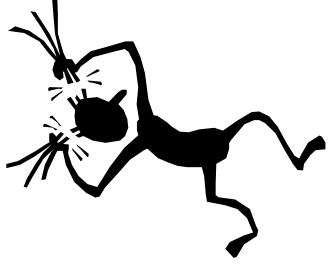
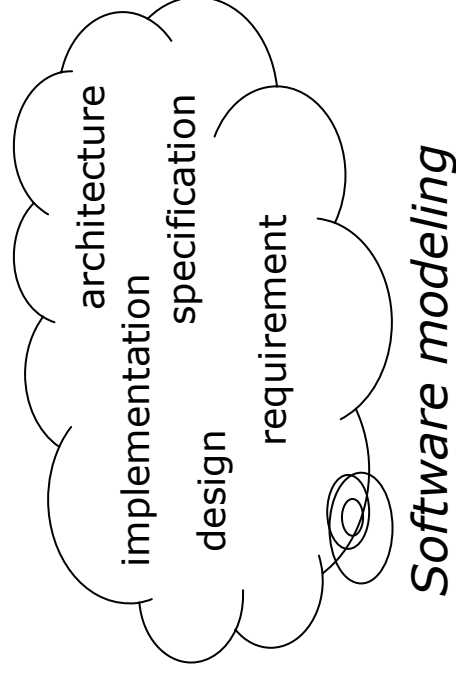
2

- Non-functional analysis and software development
- Model-driven performance analysis
- Model-driven reliability analysis
- Model-driven tradeoff analysis
- Tool support
- Research perspectives

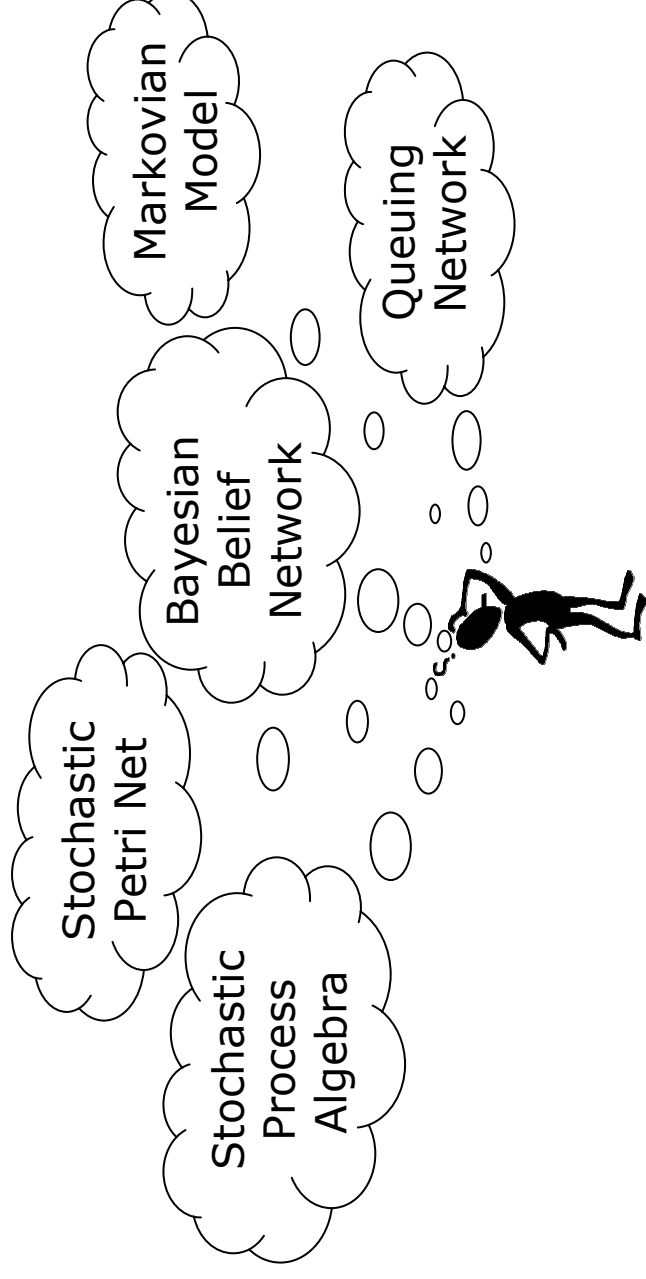
Non-functional analysis of software

3

Software modeling domain (vocabulary) is intrinsically distant from non-functional analysis one.



Reluctance to embed non-functional modeling and analysis in the software development process.



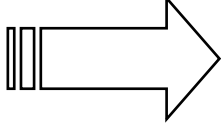
"Human made" (ad-hoc) non-functional models :
difficult to build and prone to errors

Non-functional analysis of software

5

A new vision in non-functional analysis (1998-today)

**Introducing automation to generate
non-functional models from software models**

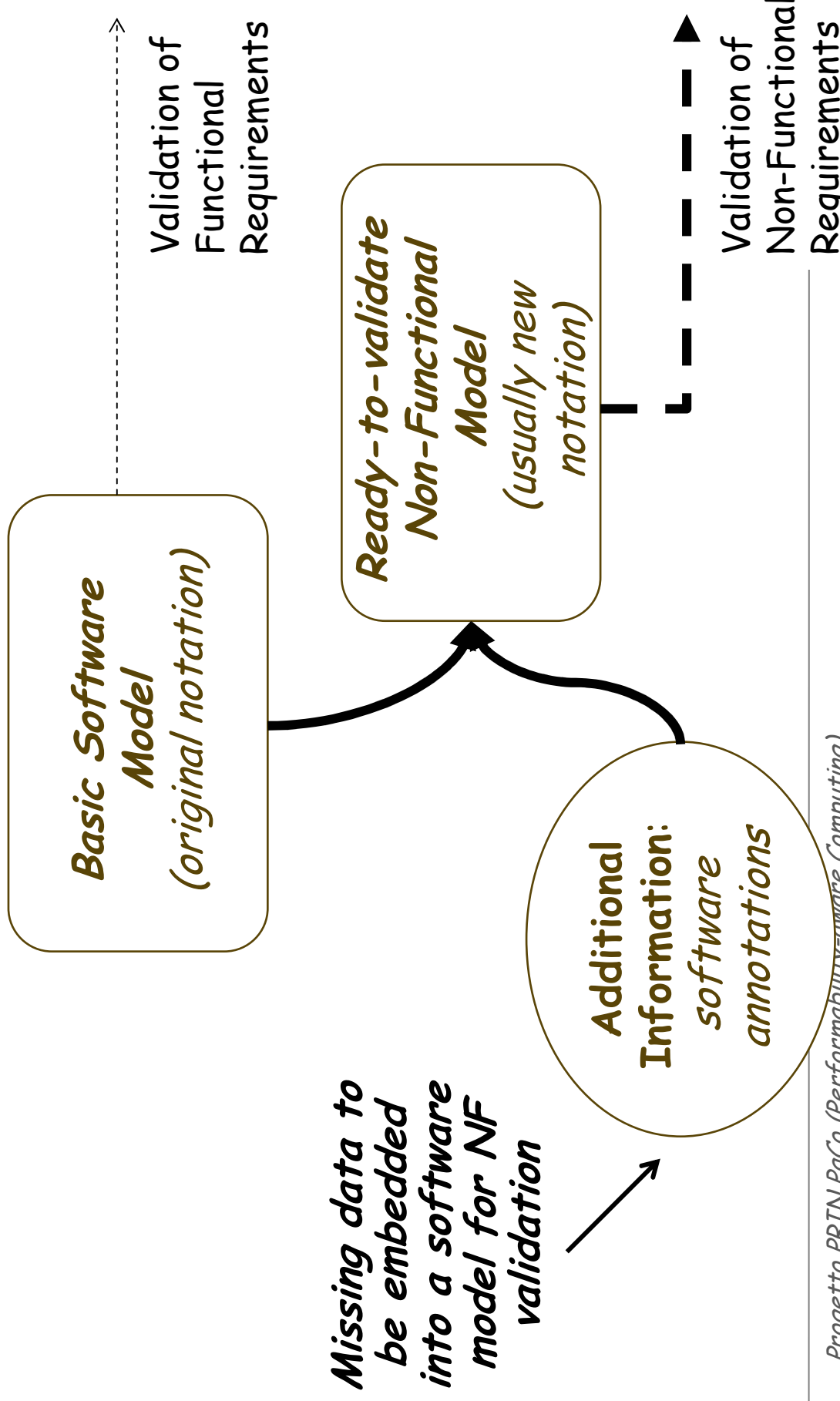


**Big effort devoted to design model transformations
having performance/reliability/... models as targets**

Non-functional analysis of software:

a general schema

6



Model annotations

7

In UML the **MARTE** Specification shall play the role of “container” of concepts related to non-functional attributes

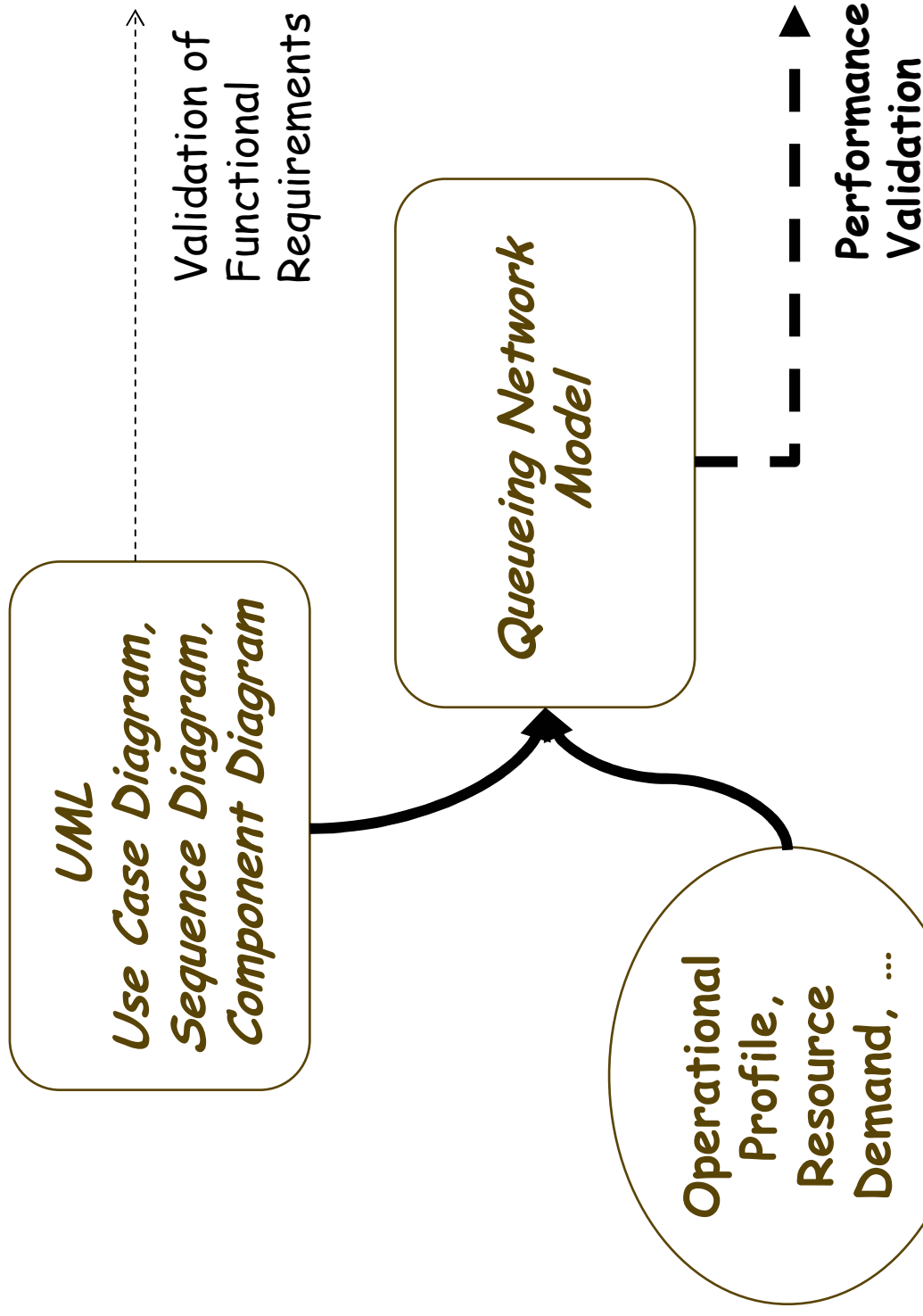
OMG, A UML Profile for MARTE, ptc/07-08-04

All **non-UML** notations that intends to embed non-functional concepts have to define **appropriate syntax and semantics** for those concepts

In general, different non-functional attributes share more than one concept, thus it may be reasonable to design “core” specifications for common concepts plus **specific concepts** for each attribute

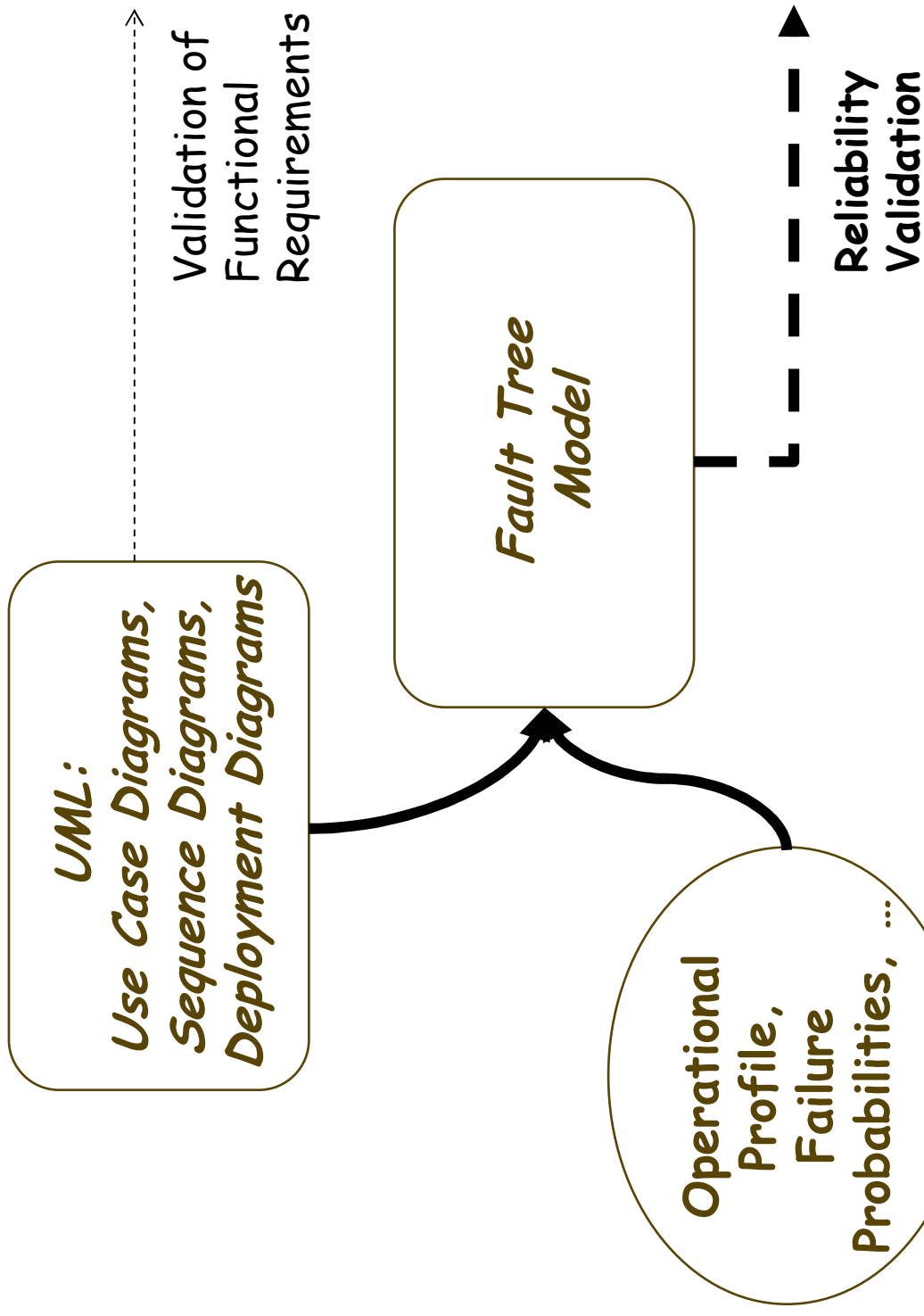
Non-functional analysis of software: an instance of the schema...

8



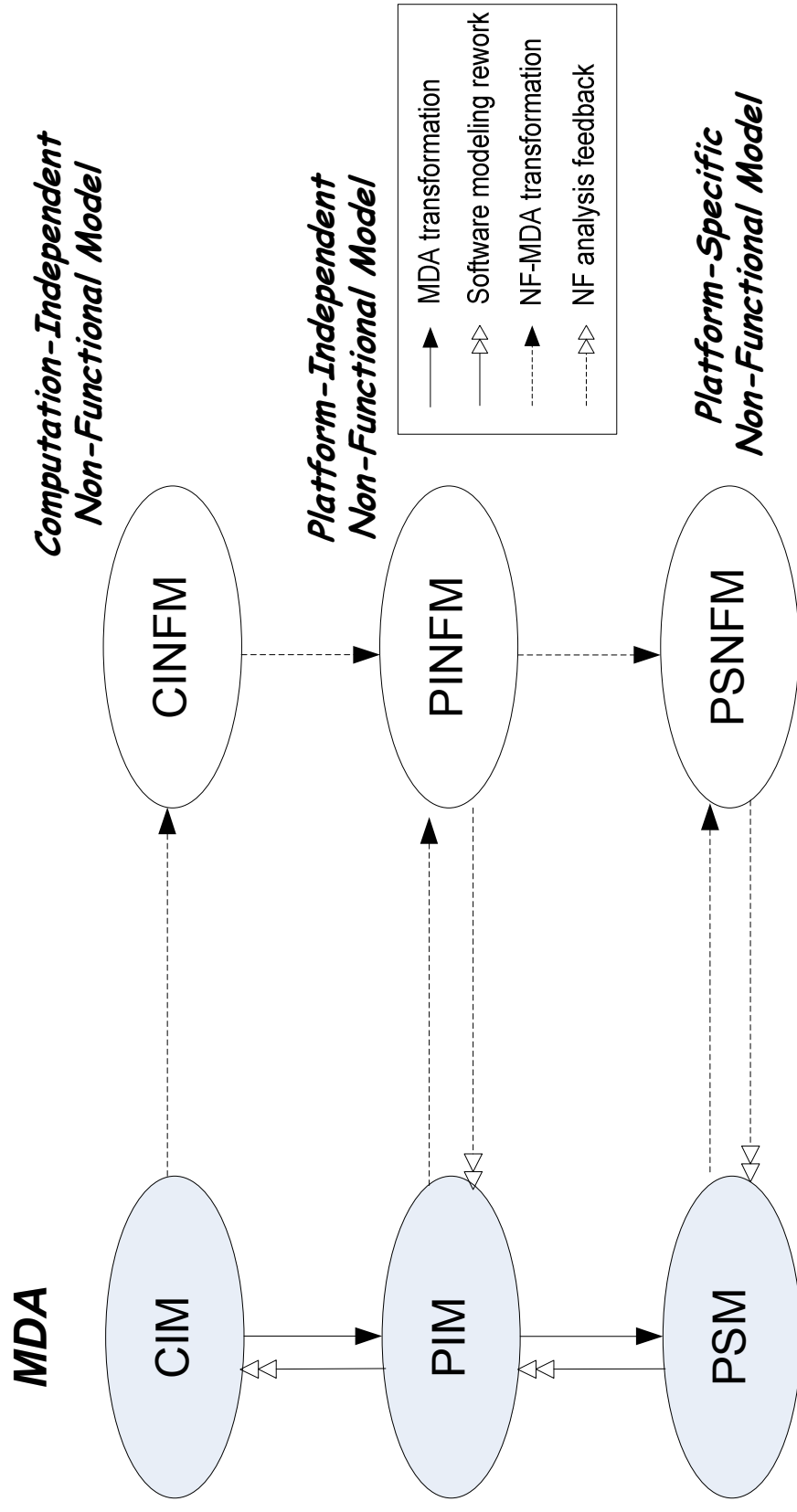
Non-functional analysis of software: ... and yet another instance

9



Non-functional models in Model-Driven Architecture

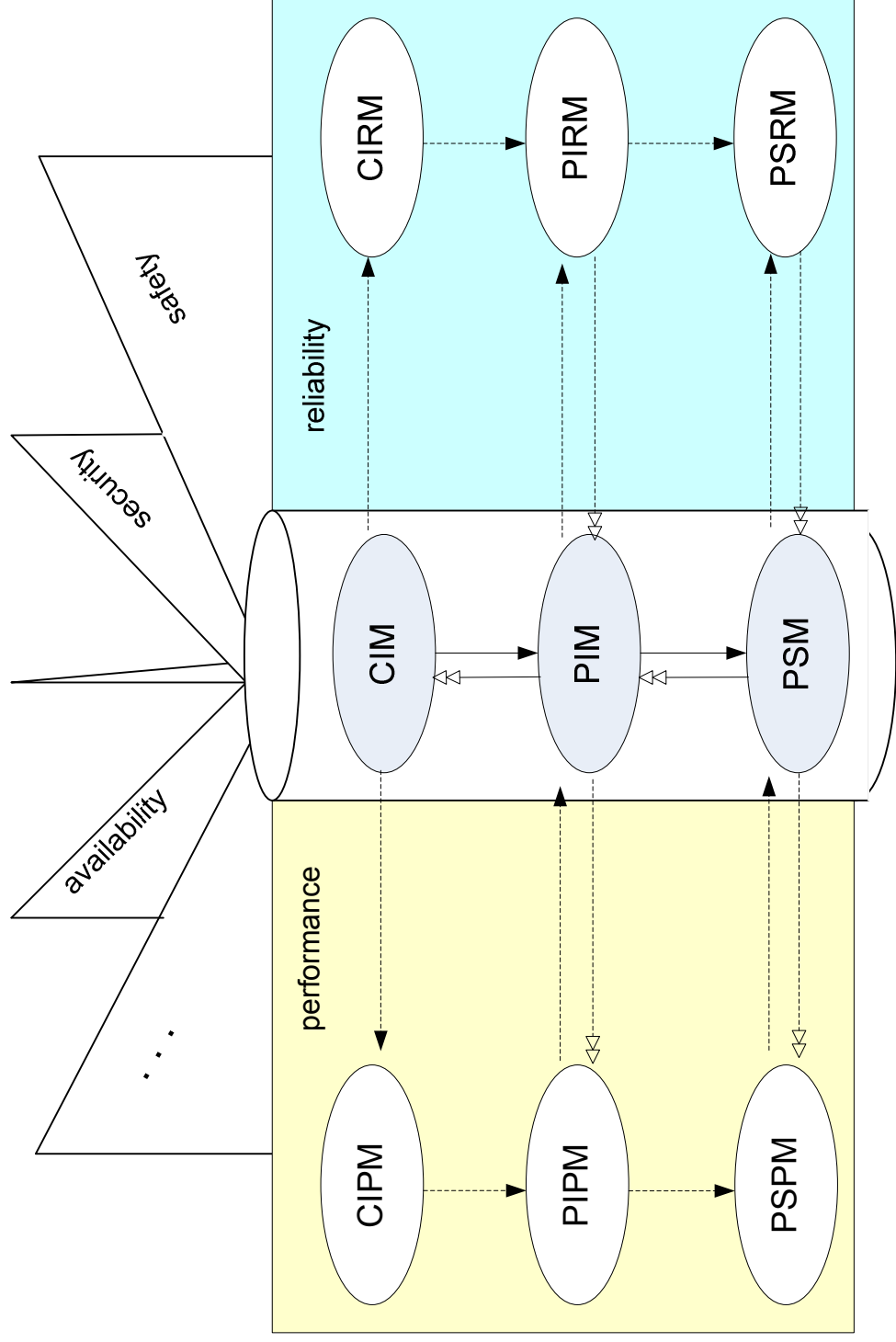
10



Horizontal and vertical transformations

Non-functional models in Model-Driven Architecture

11



Non-functional models in Model-Driven Architecture

12

- Systematic embedding of non-functional modeling and analysis in a model-driven development process
- **Automation** is the key to allow a real integration of these activities **within** the process
- The definition of **CINFM**, **PINFM**, **PSNFM** may not be trivial (or may be nonsense) for certain non-functional attributes
- The same consideration applies to the **additional transformations** introduced in **NFMDA**

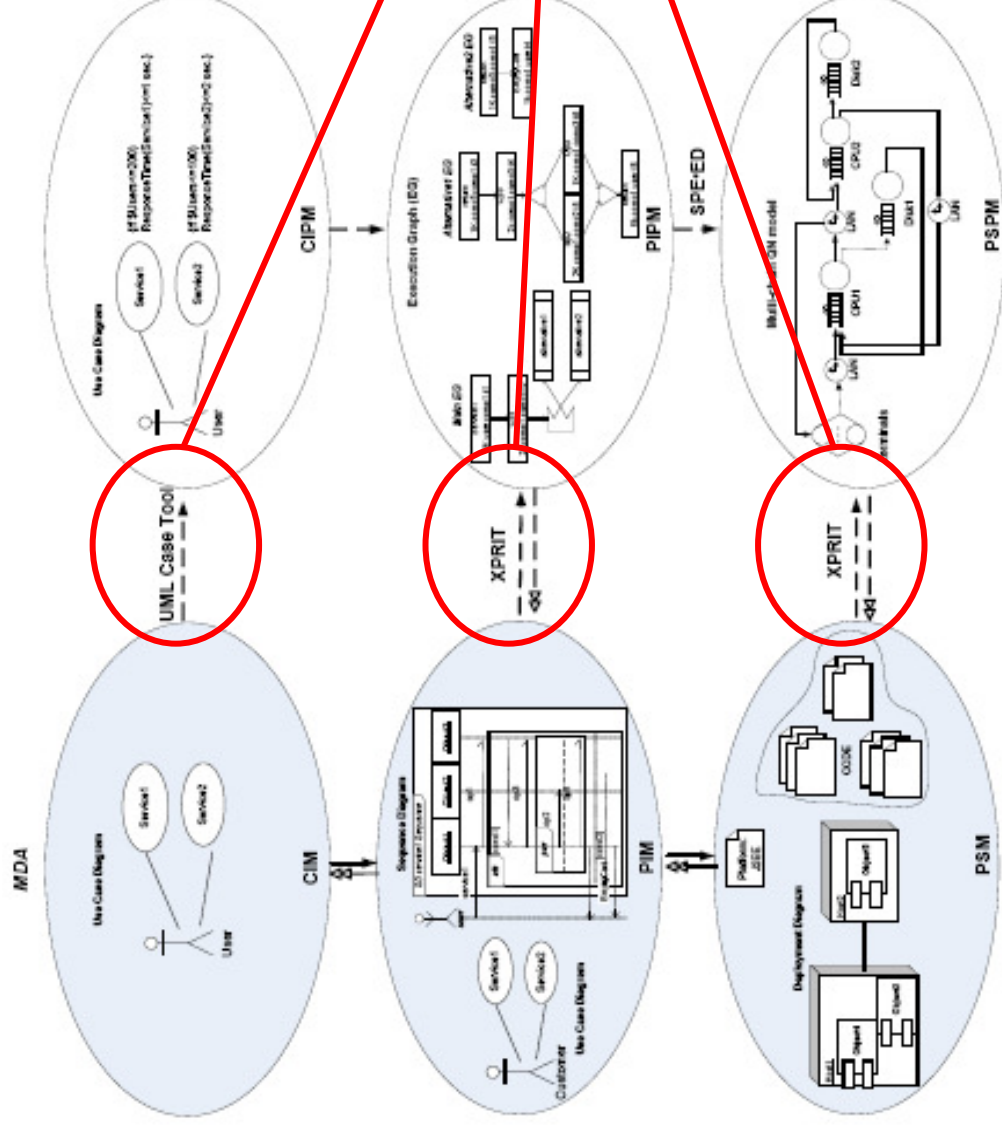
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13

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Software Performance MDA: XPRIT methodology

14

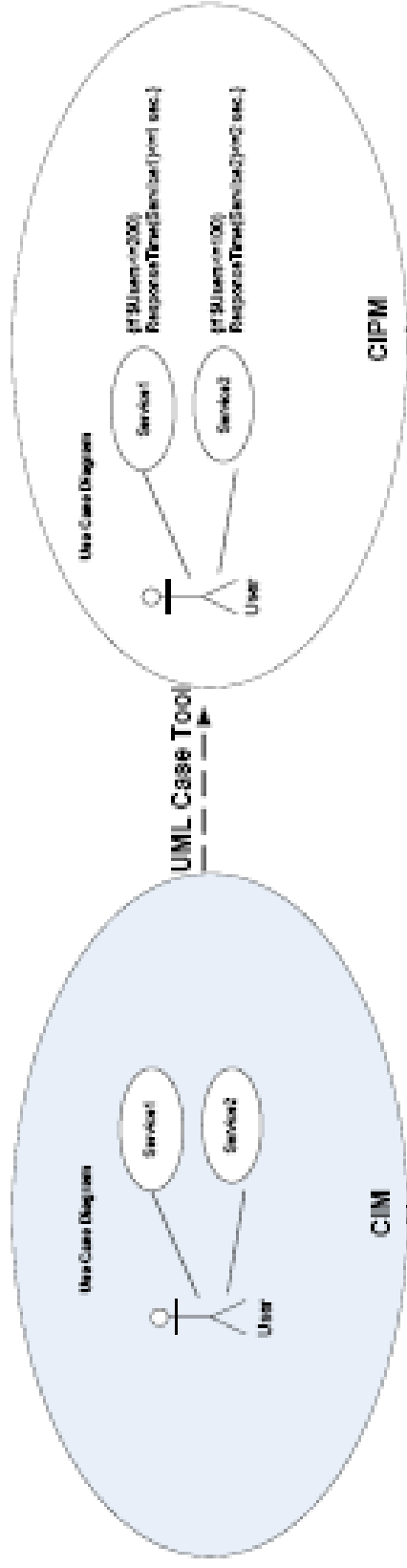


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Software Performance MDA:

CIM $\longrightarrow$ CIPM

15

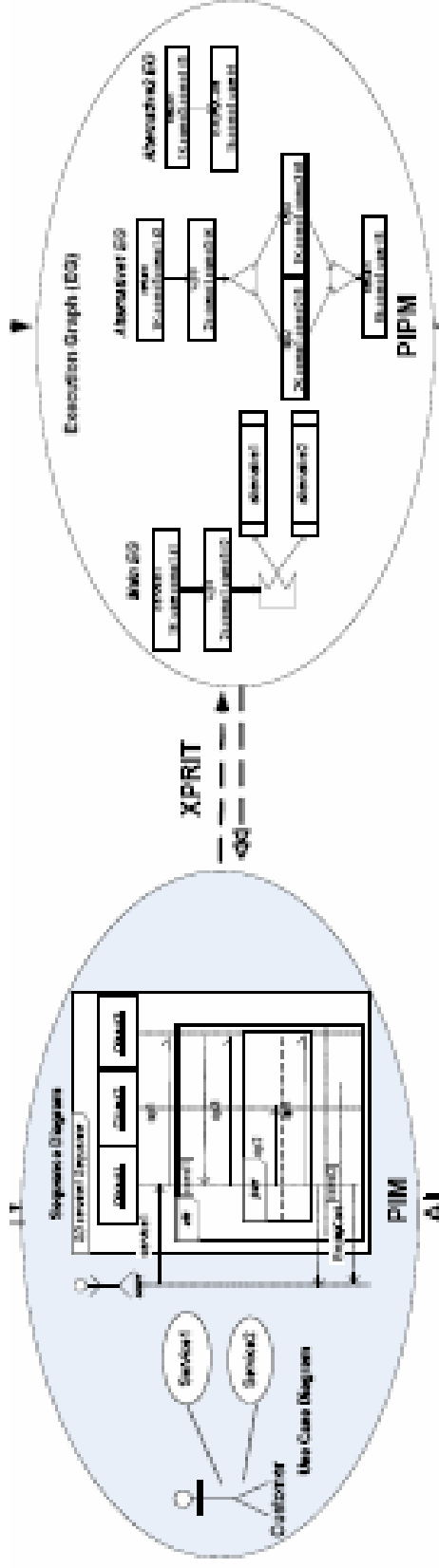


Performance requirements are annotated
on a Use Case Diagram

Software Performance MDA:

PIM $\longrightarrow$ PIPM

16

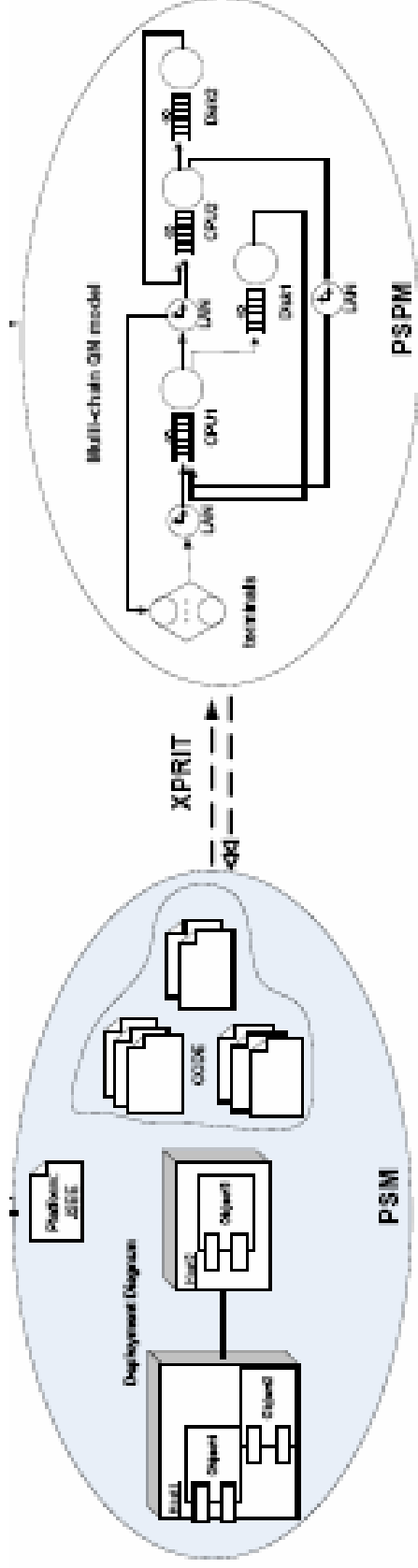


Software dynamics is annotated with **operational profile** and **resource demands** and transformed in **Execution Graphs**

At a limited extent, performance analysis can be carried out at **Platform Independent level**

Software Performance MDA:

PSM $\longrightarrow$ PSPM



A Deployment Diagram is annotated with **device characteristics** and transformed into a **Queuing Network** representing the **computational platform**

Workload is synthesized from the Execution Graphs (PIPM)

Performance analysis embedding **resource contention** is carried out at Platform Specific level

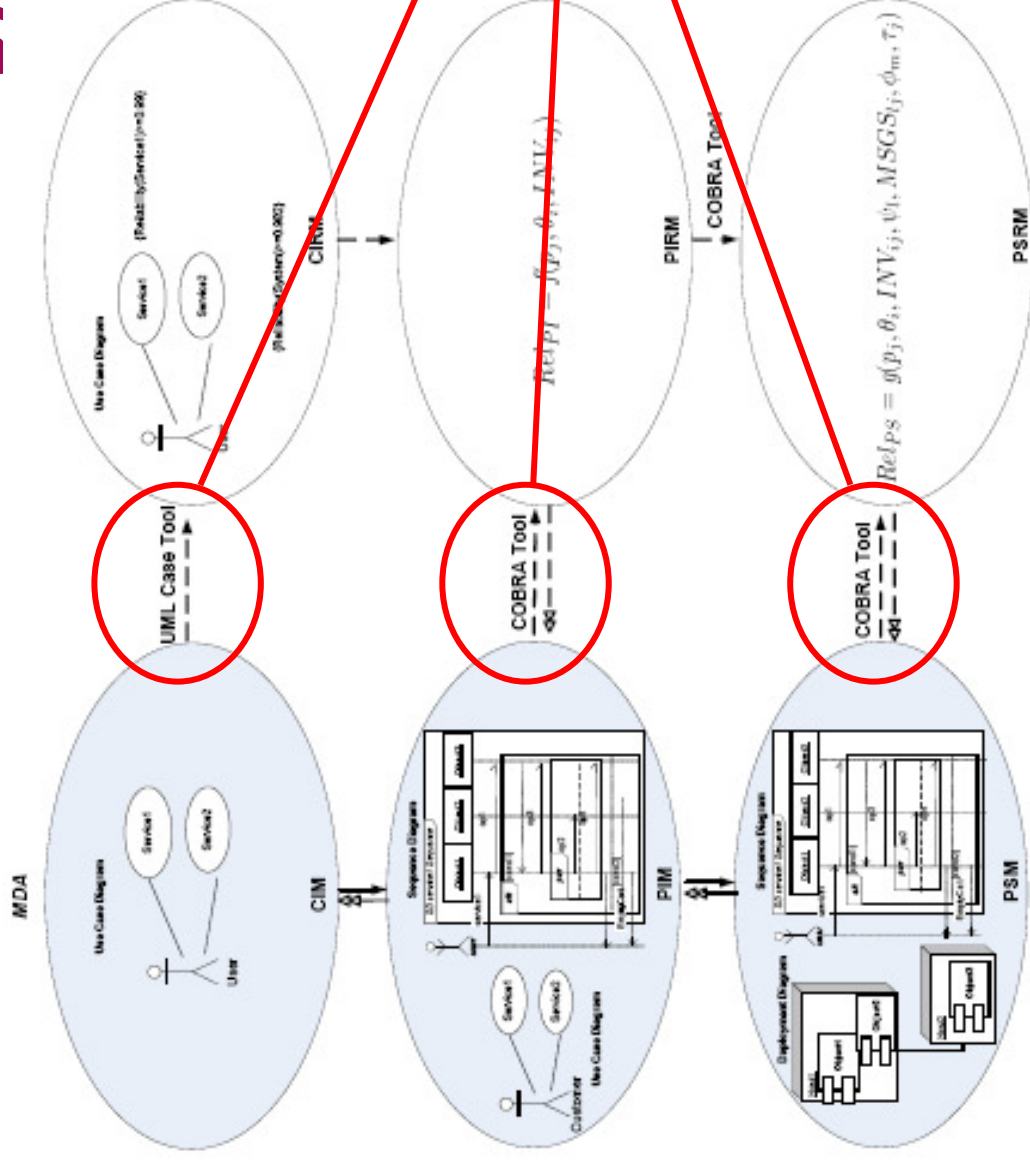
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18

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Software Reliability MDA: COBRA methodology

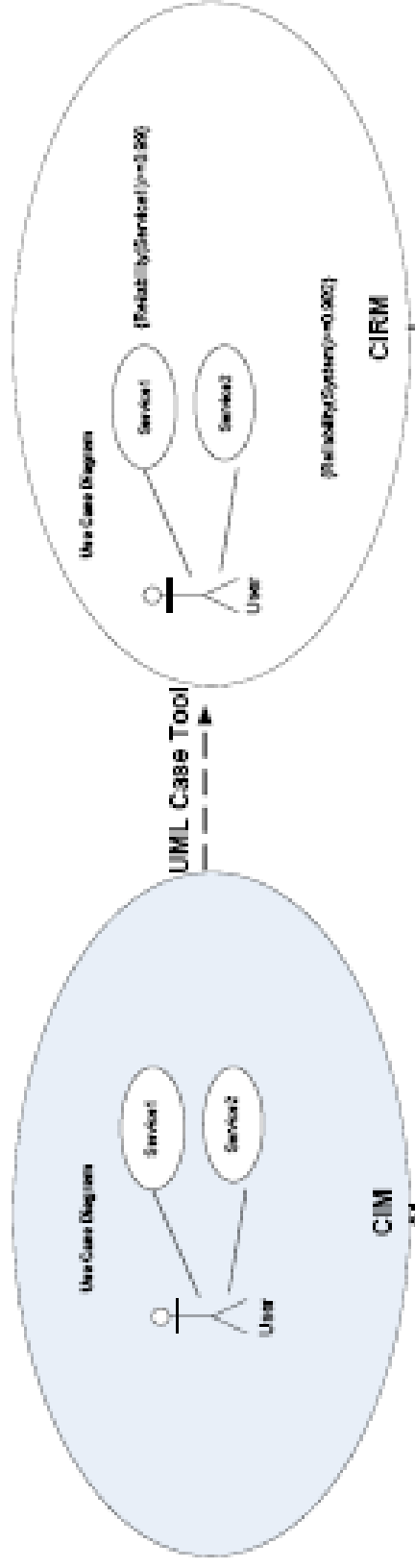
19



Software Reliability MDA:

CIM $\rightarrow$ CIRM

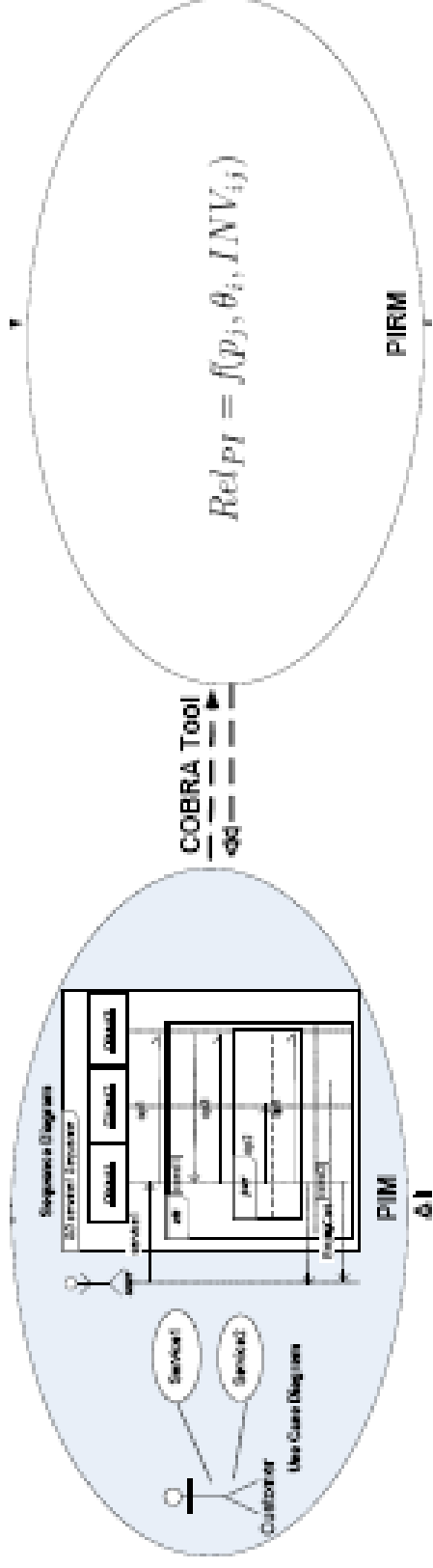
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Reliability requirements are annotated on
a Use Case Diagram

Software Reliability MDA:

PIM $\longrightarrow$ PIRM

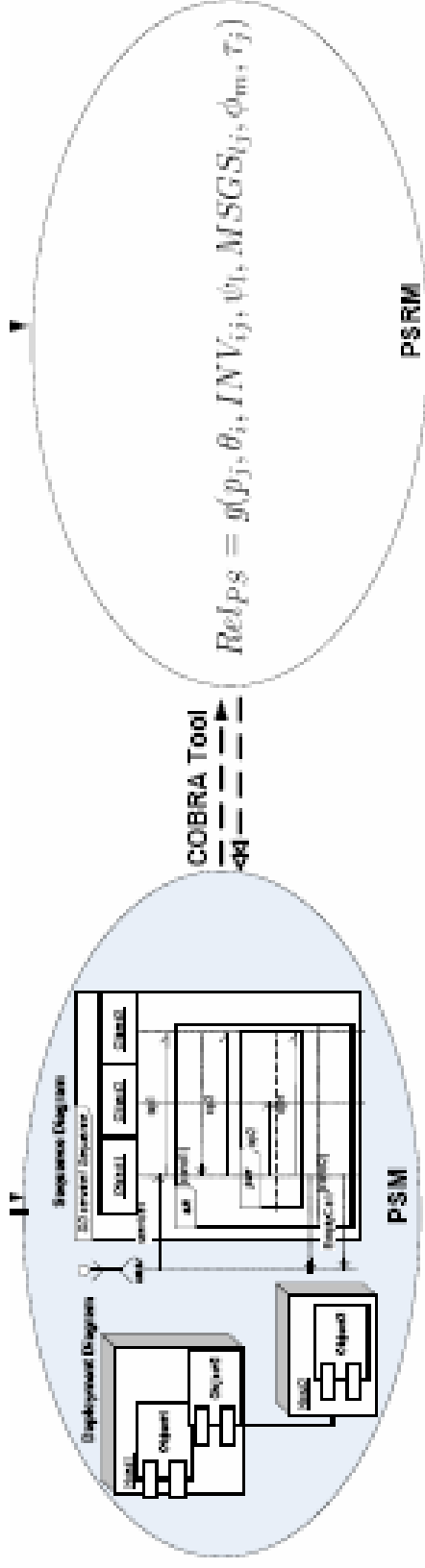


Software dynamics is annotated with **operational profile** and **probabilities of software component failures** and transformed into a **function** (of random variables)

Reliability analysis (only based on **software failures**) can be carried out at Platform Independent level

Software Reliability MDA:

PSM $\longrightarrow$ PSRM



A Deployment Diagram is annotated with **hardware failure** (sites and connectors) **probabilities** and transformed in **another function** (of random variables)

Reliability analysis (based on **software and hardware failures**) can be carried out at Platform Specific level

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23

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Model-driven tradeoff analysis

24

1. Optimization models for cost/quality tradeoffs
2. A compositional approach to security/performance tradeoff

Model-driven tradeoff analysis

25

1. Optimization models for cost/quality tradeoffs
2. A compositional approach to security/performance tradeoff

Search-Based Software Engineering

26

It is inspired by the observation that many activities in software engineering can be **formulated as optimization problems**

SOFTWARE ENGINEERS

Metaheuristic search techniques, like genetic algorithms, simulated annealing and **tabu search**, to find near optimal or good-enough **solutions**

OPERATIONAL RESEARCHERS

Exact optimization techniques of operation research like **linear or dynamic programming**

The (class of) problem(s) faced

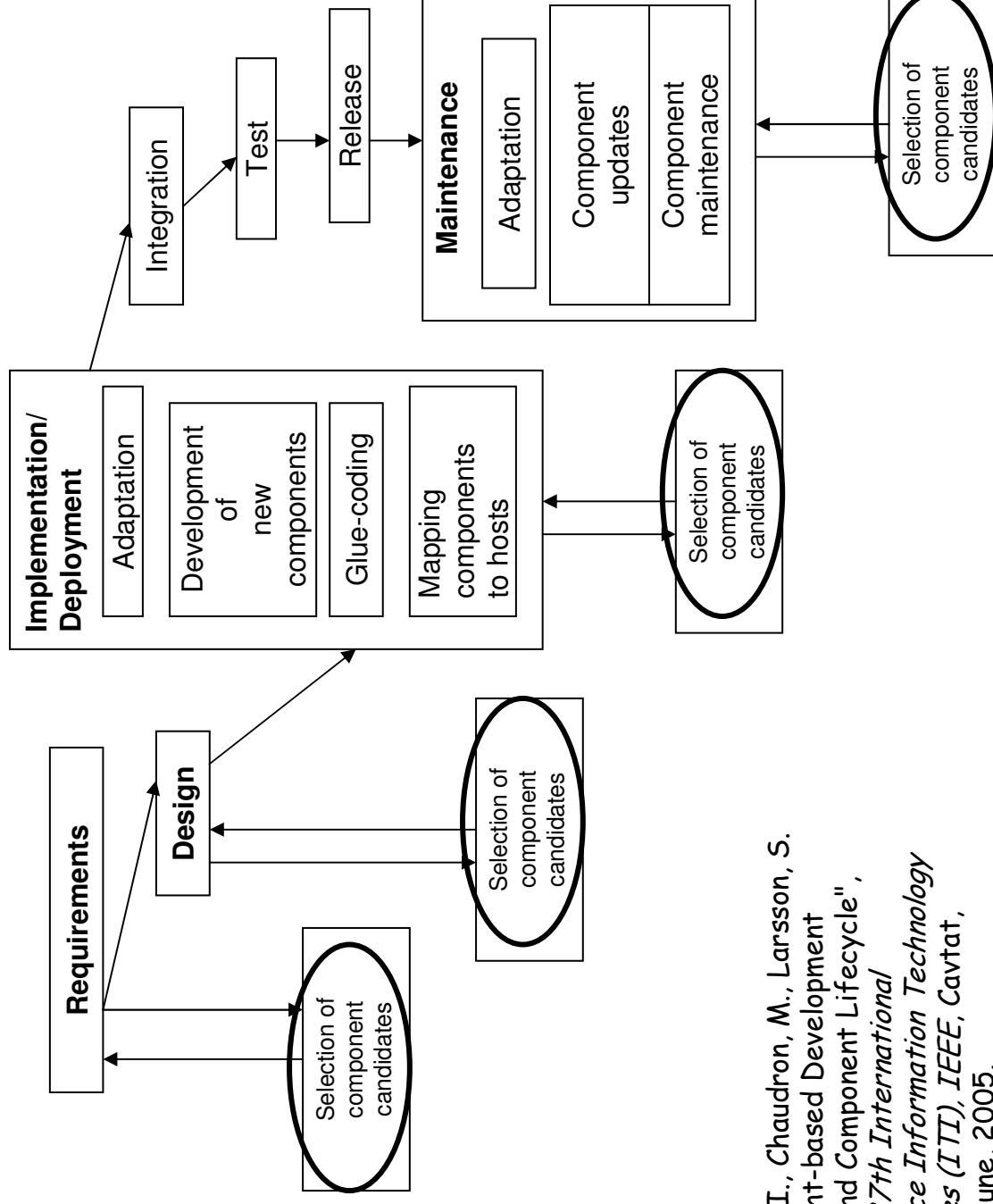
27

Studying the tradeoffs between software cost and other non-functional attributes (such as reliability and performance) in different phases of the software lifecycle

We have tackled this problem under the development paradigm of **Component-Based Software Engineering** in relationship to the selection of components

Selection of components and lifecycle

28



Crnkovic, I., Chaudron, M., Larsson, S.
 "Component-based Development
 Process and Component Lifecycle",
*Proc. of 27th International
 Conference Information Technology
 Interfaces (ITI), IEEE, Cavtat,
 Croatia, June, 2005.*

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Selection of components and lifecycle

29

- Human-based search
- Usually based only on functional characteristics of components
- Non-functional characteristics of components make the quality of a software product
- SBSE may help to raise the focus of software engineers from manual selection to model parameterization
- Efficient model solution techniques may allow to quickly analyze multiple alternatives

Selection of components and lifecycle

30

The problem

Selection of components driven by non-functional properties in Component-based Systems

REQUIREMENTS PHASE

Cost vs satisfaction of requirements

ARCHITECTURAL DESIGN PHASE

Cost vs reliability and delivery time

IMPLEMENTATION/DEPLOYMENT PHASE

Cost vs reliability and completion time

Architectural Design Phase

31

We have introduced an optimization model that determines **the instance to choose for each component** (either one of the available COTS products or an in-house developed one) in order to minimize the software costs under delivery time and reliability constraints.

In addition, the solution provides **the amount of testing** to be performed on each in-house component in order to achieve a certain reliability level.

Architectural Design Phase

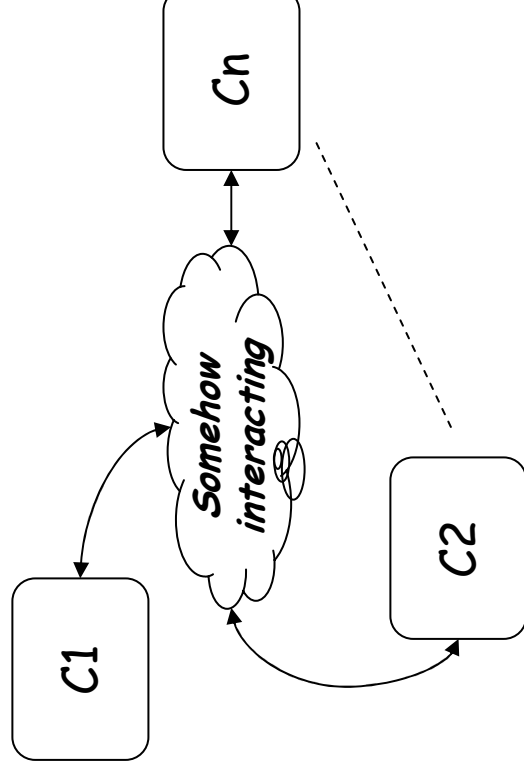
32

We assume in this phase that the architecture of the software system has been designed

- All functionally equivalent
- They differ for cost and non-functional properties

For each component i :

$\bar{J}_i$ is a set of instances that can be in-house developed
 J_i is a set of COTS instances that can be bought



VARIABLES

In general, a “build-or-buy” decisional strategy can be described as a set of 0/1 variables defined as follows ($\forall i = 1, \dots, n$):

$$x_{ij} = \begin{cases} 1 & \text{if instance } C_{ij} \text{ is chosen } (j \in J_i \text{ or } j \in \bar{J}_i) \\ 0 & \text{otherwise} \end{cases}$$

The variables must fulfill the following constraints:

$$\sum_{j \in J_i \cup \bar{J}_i} x_{ij} = 1, \quad \forall i = 1, \dots, n$$

For each component i , exactly one instance is either bought as COTS or in-house developed.

COST OBJECTIVE FUNCTION

We express the Cost Objective Function as follows:

$$\sum_{i=1}^n \left(\sum_{j \in J_i} \bar{c}_{ij} (t_{ij} + \tau_{ij} N_{ij}^{tot}) x_{ij} + \sum_{j \in J_i} c_{ij} x_{ij} \right)$$

**Development
cost of a
in-house
instance**

For each instance j and component i let:

$\bar{c}_{ij}$ be the unitary development cost

τ_{ij} be the average time
required to perform a test

t_{ij} be the estimated development time

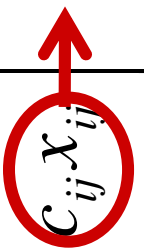
case

- Cost of an in-house instance : development cost plus testing cost
- N_{ij}^{tot} (additional variable) : number of tests on in-house instance j of i

COST OBJECTIVE FUNCTION

We express the Cost Objective Function as follows:

$$\sum_{i=1}^n \left(\sum_{j \in J_i} \bar{c}_{ij} (t_{ij} + \tau_{ij} N_{ij}^{tot}) x_{ij} + \sum_{j \in J_i} c_{ij} x_{ij} \right)$$


Cost of a COTS component

For each instance j and component i let:

c_{ij} be the buying cost

DELIVERY TIME CONSTRAINT

A maximum threshold T is given on the delivery time of the whole system.

The following expression represents the delivery time of the component i :

$$\sum_{j \in J_i} (t_{ij} + \tau_{ij} N_{ij}^{tot}) x_{ij} + \sum_{j \in J_i} d_{ij} x_{ij}$$

Delivery time
of an in-house
instance.

For each instance j and component i let:

t_{ij} be the estimated development time

τ_{ij} be the average time required to perform a test case

DELIVERY TIME CONSTRAINT

A maximum threshold T is given on the delivery time of the whole system.

The following expression represents the delivery time of the component i :

$$\sum_{j \in J_i} (t_{ij} + \tau_{ij} N_{ij}^{tot}) x_{ij} + \sum_{j \in J_i} d_{ij} x_{ij}$$

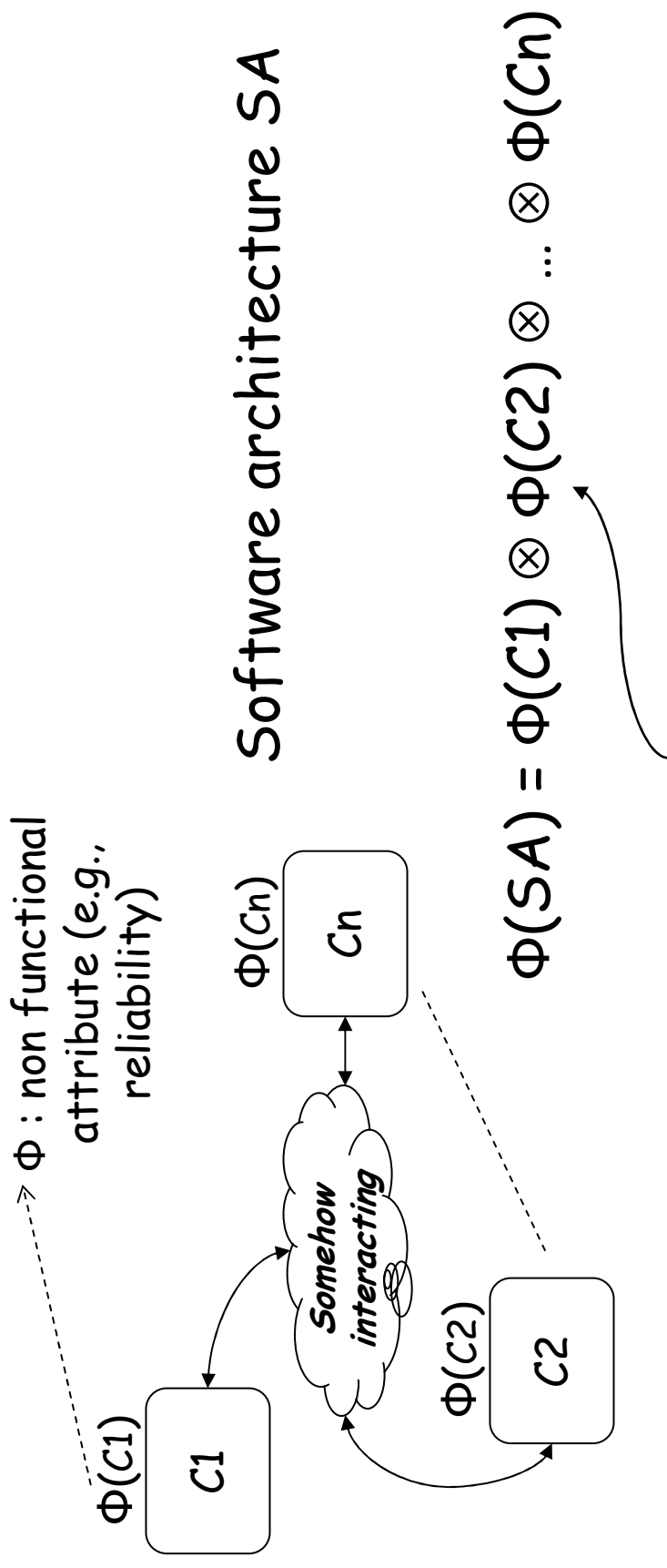
Delivery time of a COTS component

For each instance j and component i let:

d_{ij} be the delivery time

RELIABILITY CONSTRAINT

A minimum threshold R is given on the reliability of the whole system.



It is not easy to express the relationships between non-functional characteristics of components and quality of the whole system

RELIABILITY CONSTRAINT

$$REL(SA) = \prod_{i=1}^n \phi_i$$

Jung H.W. et al. "Selecting Optimal COTS Products Considering Cost and Failure Rate", *Proc. of ISSRE*, 1999.

$$\phi_i = e^{-fnum_i}$$

the average number of failures of a component instance

$$fnum_i = \sum_{j \in J_i} \theta_{ij} s_{ij} x_{ij} + \sum_{j \in J_i} \mu_{ij} s_{ij} x_{ij}$$

The probability of failure on demand θ_{ij} of the in-house developed instance C_{ij}

$$\theta_{ij} = \frac{Testab_{ij} * p_{ij} (1 - Testab_{ij})^{N_{ij}^{suc}}}{(1 - p_{ij}) + p_{ij} (1 - Testab_{ij})^{N_{ij}^{suc}}}$$

the number of successful (i.e. failure free) tests performed on an in-house instance

Bertolino, A. and Strigini, L.: "On the use of testability measures for dependability assessment", *on Software Engineering*, 22(2):97-108, February, 1996.

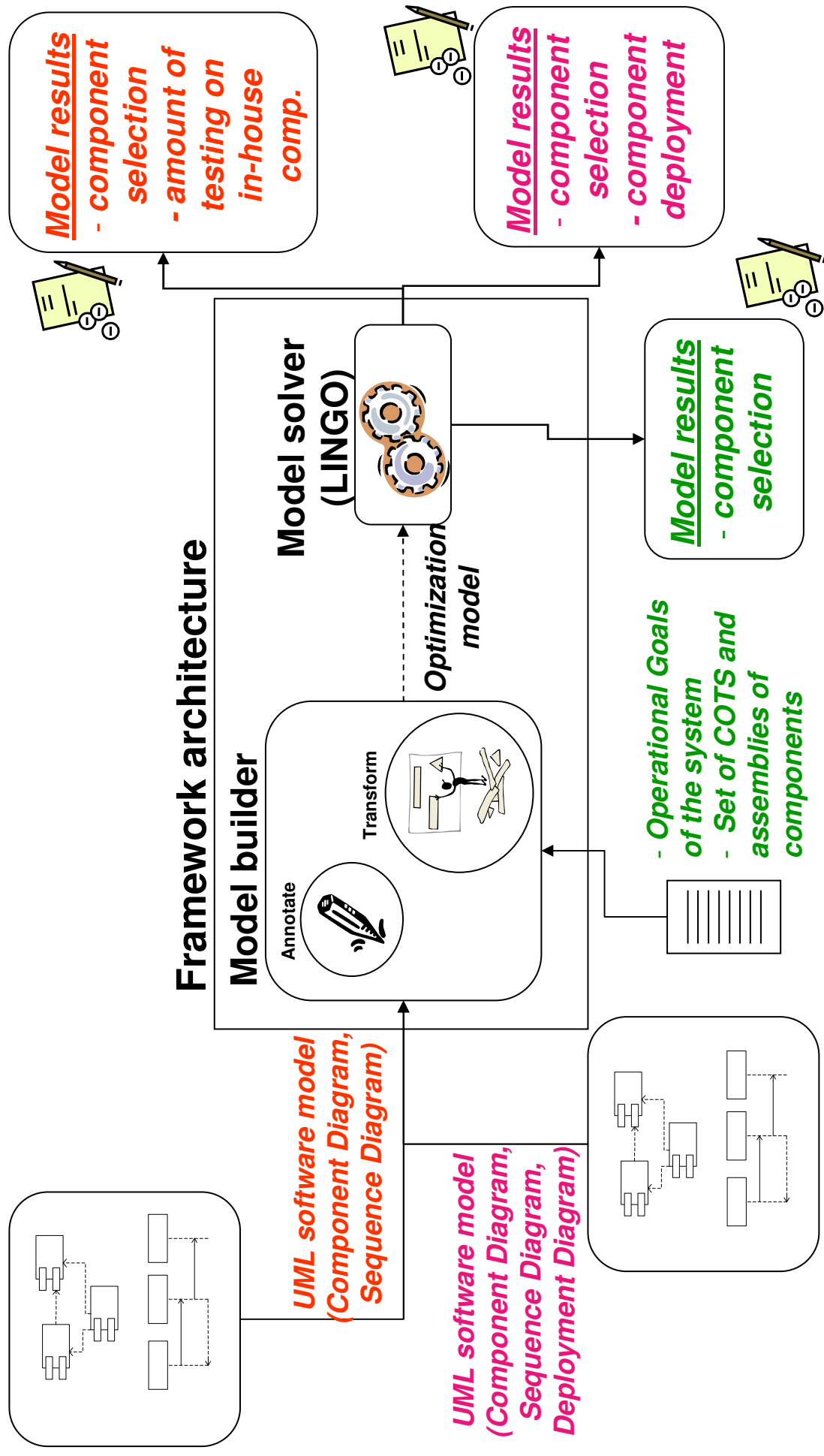
OPTIMIZATION MODEL

40

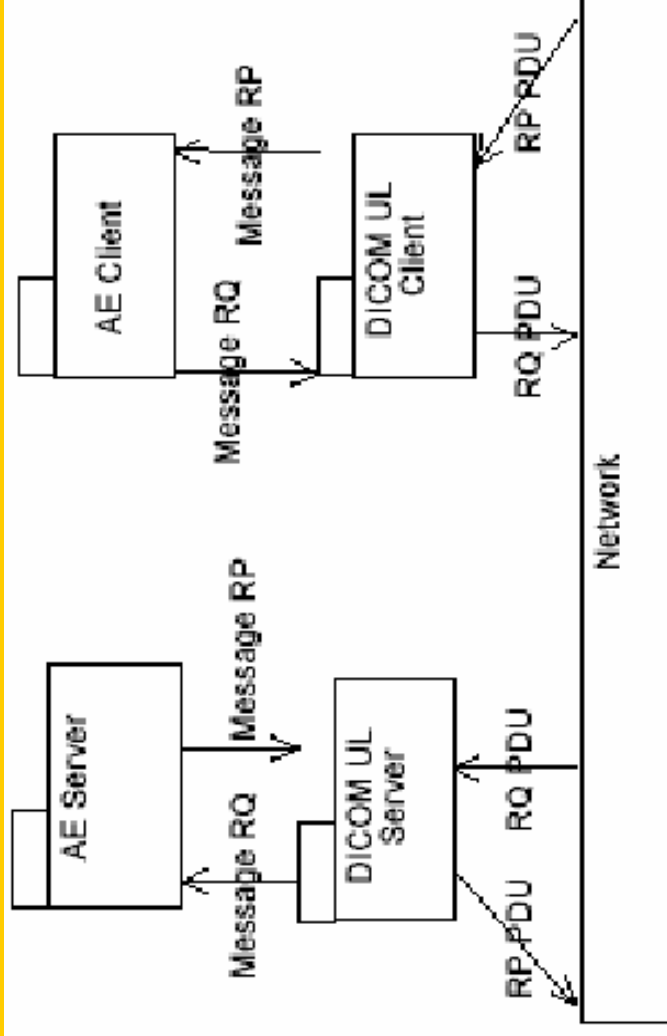
$$\begin{aligned}
 \min \quad & \sum_{i=1}^n \left[\sum_{j \in \bar{J}_i} \bar{c}_{ij} (t_{ij} + \tau_{ij} N_{ij}^{tot}) x_{ij} + \sum_{j \in J_i} c_{ij} x_{ij} \right] \\
 \max \quad & \left(\sum_{j \in \bar{J}_i} (t_{ij} + \tau_{ij} N_{ij}^{tot}) x_{ij} + \sum_{j \in J_i} d_{ij} x_{ij} \right) \leq T \\
 \prod_{i=1}^n e^{-\left(\sum_{j \in \bar{J}_i} \theta_{ij} s_i x_{ij} + \sum_{j \in J_i} \mu_{ij} s_i x_{ij} \right)} & \geq R \\
 \sum_{j \in \bar{J}_i \cup \bar{J}_i} x_{ij} = 1, \forall i = 1, \dots, n & \\
 x_{ij} \in \{0,1\}, \forall i = 1, \dots, n, \forall j \in J_i \cup \bar{J}_i &
 \end{aligned}$$

A framework for component selection

41

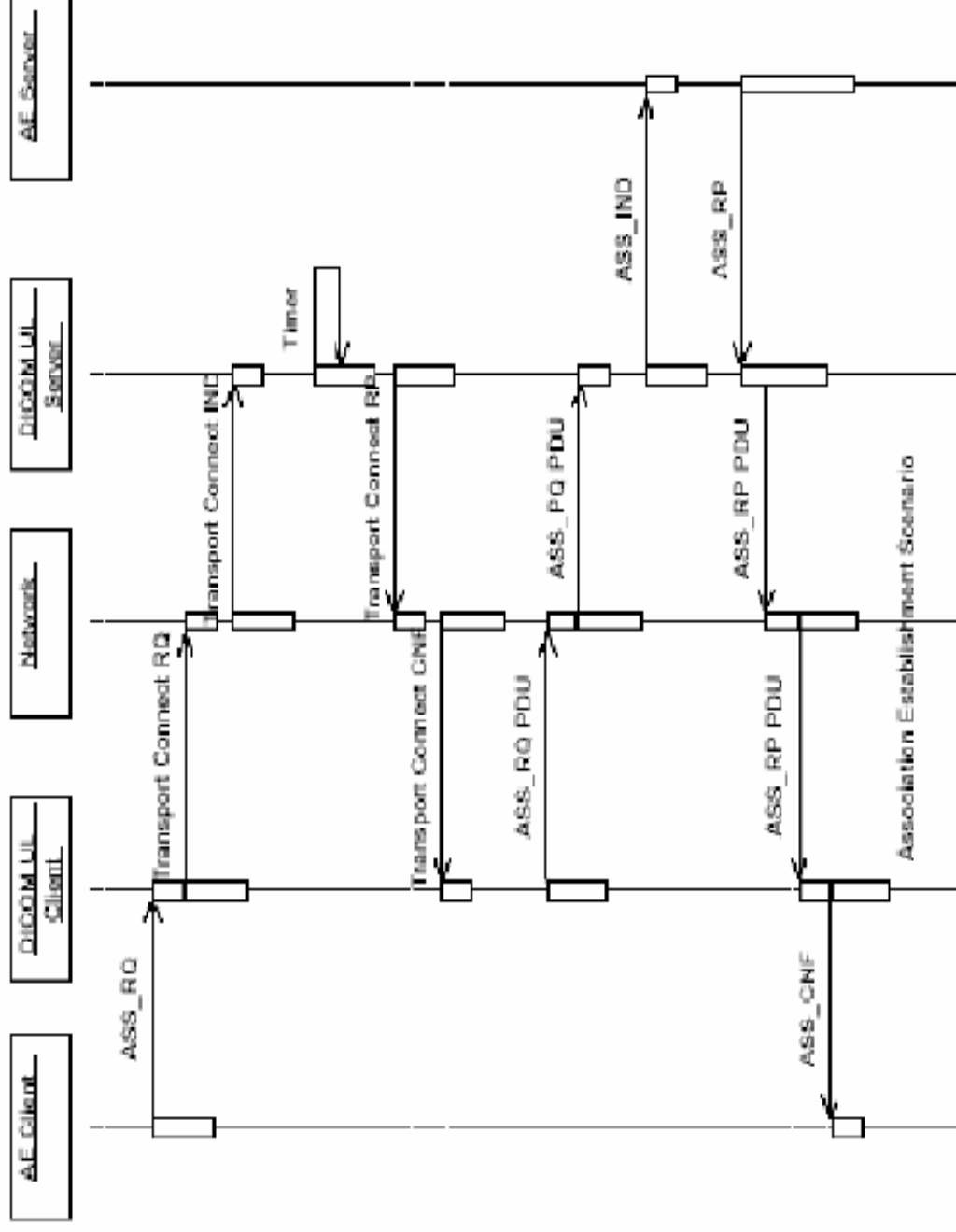


An example: a distributed medical system



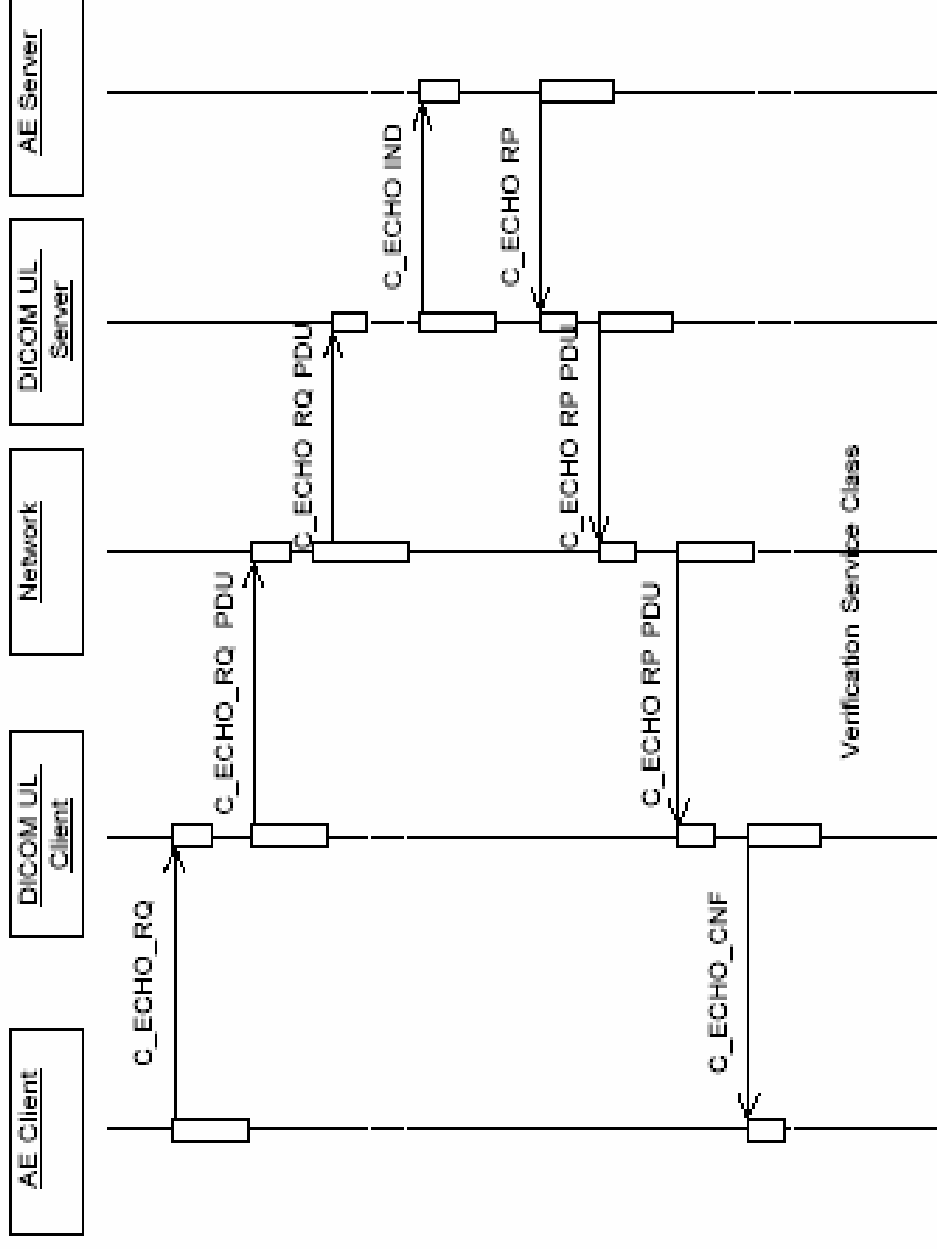
It is a client/server system, where the *AE Client* subsystem is connected via a network (*Network* subsystem) to the *AE Server* subsystem. The communication between the entities of the system is performed using Digital Imaging and Communication in Medicine (DICOM) standard, which is typically used, for example, for producing, processing and exchanging medical images.

An example: a distributed medical system



First Scenario

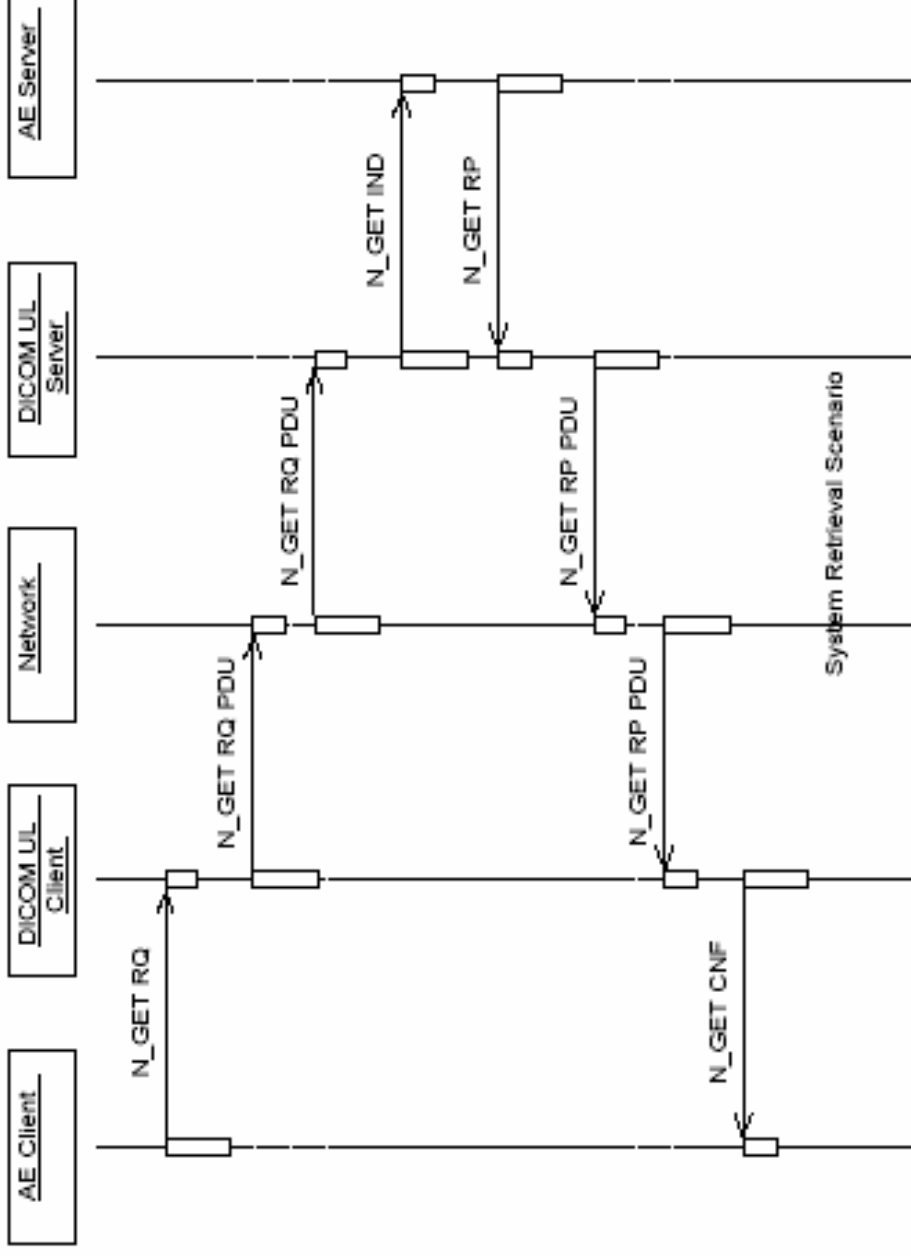
An example: a distributed medical system



Second Scenario

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An example: a distributed medical system



Third Scenario

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Kickoff Meeting, Bertinoro, 23-24 ottobre 2008*

An example: a distributed medical system

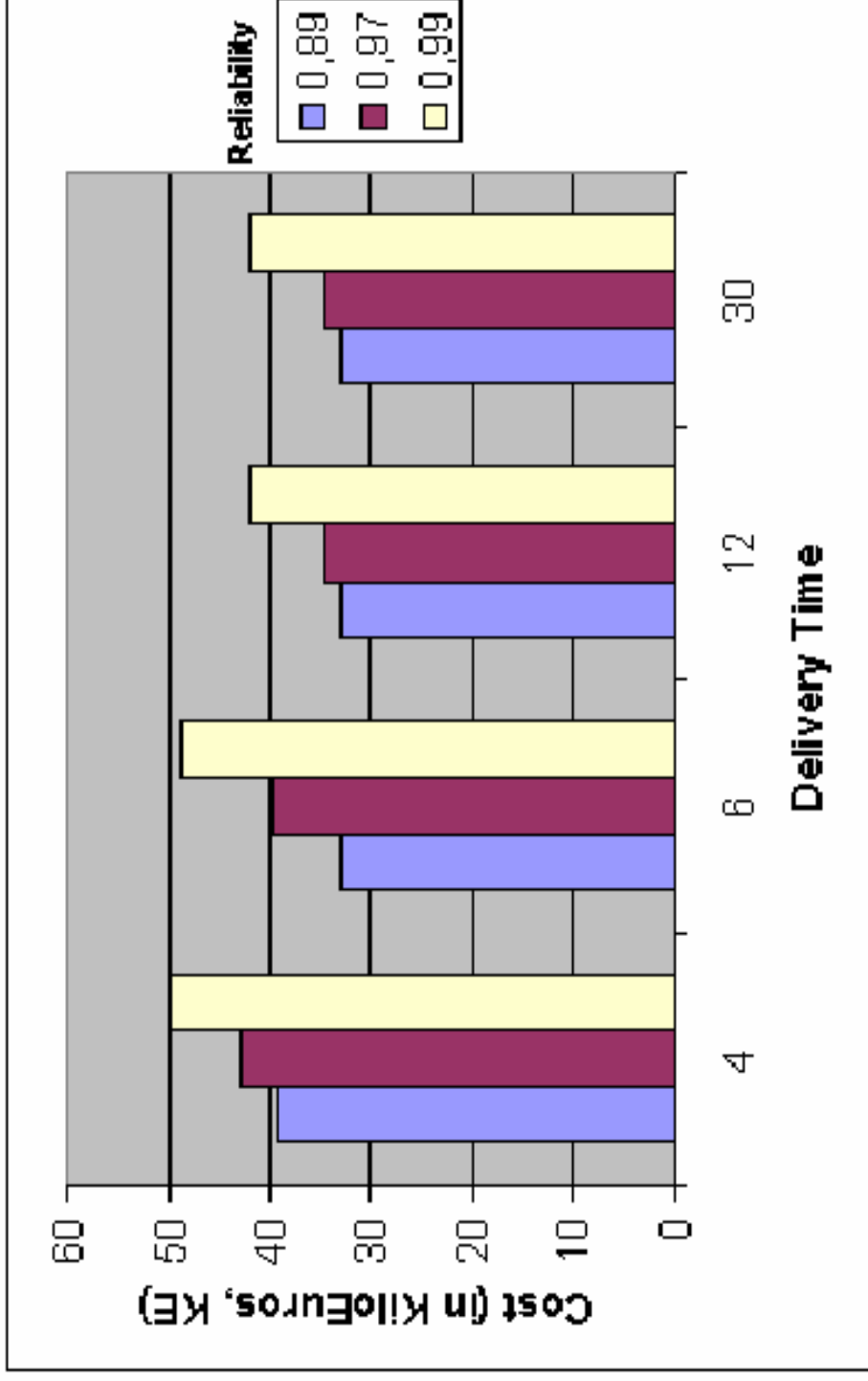
	Component name	COTS alternatives	Cost c_{ij}	Average delivery time d_{ij}	Average no. of invocations s_i	Prob. of fail. on demand μ_{ij}
C_1	AE Client	C_{11}	14	3	1.9	0.001
		C_{12}	6	3		0.11
C_2	DICOM UL Client	C_{21}	6	4	2.3	0.009
		C_{22}	12	3		0.001
		C_{23}	14	3		0.0001
C_3	Network	C_{31}	12	2	2.6	0.005
		C_{32}	14	4		0.0003
		C_{33}	15	7		0.0001
C_4	DICOM UL Server	C_{41}	5	4	2.6	0.006
		C_{42}	10	3		0.0002
C_5	AE Server	C_{51}	5	3	0.9	0.004
		C_{52}	10	5		0.0003
		C_{53}	11	5		0.000001
		C_{54}	11	7		0.0001

Parameters for COTS instances

Parameters for in-house developed components

	Component name	Development Time t_{i0}	Testing Time τ_{i0}	Unitary development cost $\bar{c}_{i0}$	Faulty Probability p_{i0}	Testability $Testab_{i0}$
C_1	AE Client					
C_2	DICOM UL Client	6	0.007	1	0.8	0.006
C_3	Network	6	0.007	1	0.8	0.009
C_4	DICOM UL Server	3	0.007	1	0.3	0.006
C_5	AE Server	4	0.007	1	0.5	0.009

Model Solution



We have solved the optimization model for multiple values of bounds T and R . The former spans from 4 to 30 whereas the latter from 0.89 to 0.99.

Model Solution

	$R=0.89$	$R=0.97$	$R=0.99$
$T=4$	$[C_{11}, C_{21}, C_{31}, (C_{40}, 0), (C_{50}, 0)]$, SysRel=0.95539 , Cost=39	$[C_{11}, C_{21}, C_{32}, (C_{40}, 128), C_{51}]$ SysRel=0.970000, Cost=42.896	$[C_{11}, C_{23}, C_{32}, (C_{40}, 139), (C_{50}, 0)]$ SysRel=0.990000, Cost=49.973
$T=6$	$[C_{11}, (C_{20}, 0), (C_{30}, 0), (C_{40}, 0), (C_{50}, 0)]$ SysRel=0.95915 , Cost=33	$[C_{11}, C_{22}, (C_{30}, 0), (C_{40}, 44), (C_{50}, 80)]$ SysRel= 0.970008 , Cost=39.868	$[C_{11}, C_{22}, C_{32}, (C_{40}, 112), (C_{50}, 137)]$ SysRel=0.99, Cost=48.743
$T=12$	$[C_{11}, (C_{20}, 0), (C_{30}, 0), (C_{40}, 0), (C_{50}, 0)]$ SysRel=0.95915, Cost=33	$[C_{11}, (C_{20}, 0), (C_{30}, 233), (C_{40}, 0), (C_{50}, 0)]$ SysRel=0.970002 , Cost=34.631	$[C_{11}, (C_{20}, 467), (C_{30}, 532), (C_{40}, 129), (C_{50}, 150)]$ SysRel=0.99, Cost=41.946
$T=30$	$[C_{11}, (C_{20}, 0), (C_{30}, 0), (C_{40}, 0), (C_{50}, 0)]$ SysRel=0.95915, Cost=33	$[C_{11}, (C_{20}, 0), (C_{30}, 233), (C_{40}, 0), (C_{50}, 0)]$ SysRel=0.970002, Cost=34.631	$[C_{11}, (C_{20}, 488), (C_{30}, 459), (C_{40}, 148), (C_{50}, 164)]$ SysRel=0.990002, Cost=41.813

**Optimal solution for all previous cases
(i.e. selection of components and number of tests)**

Model-driven tradeoff analysis

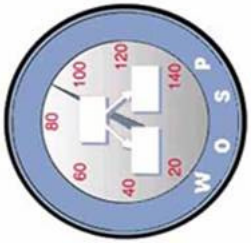
49

1. Optimization models for cost/quality tradeoffs
2. A compositional approach to security/performance tradeoff

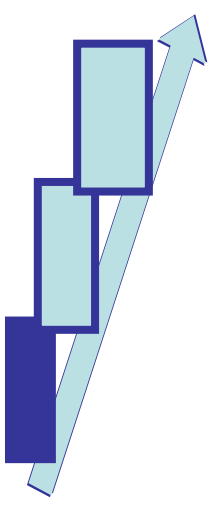
A compositional approach to security/performance tradeoff

50

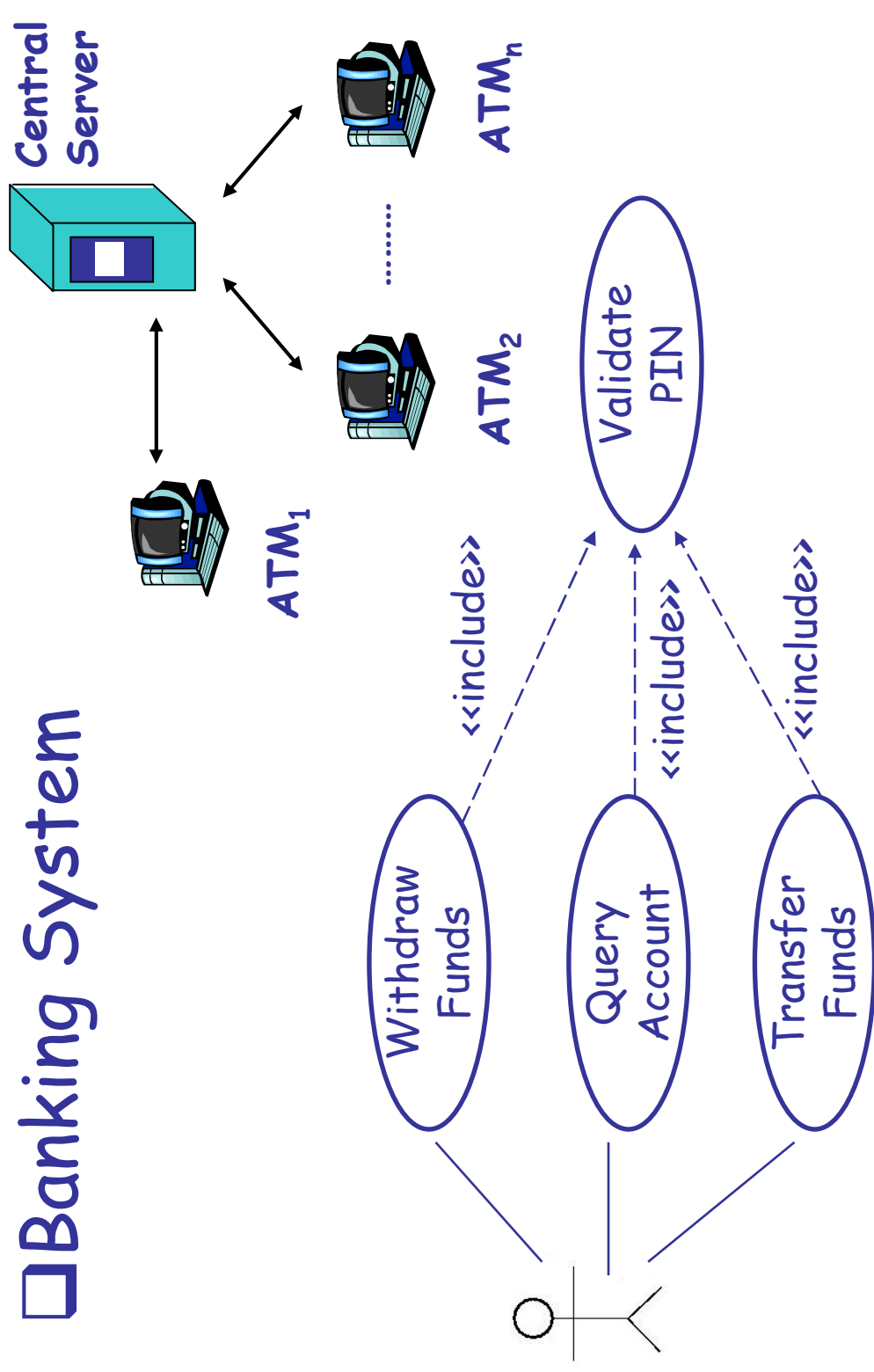
Do we have time for it now?

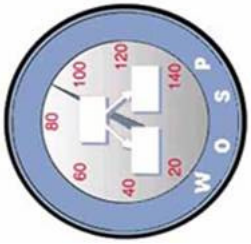


Experimentation: *Application Model*



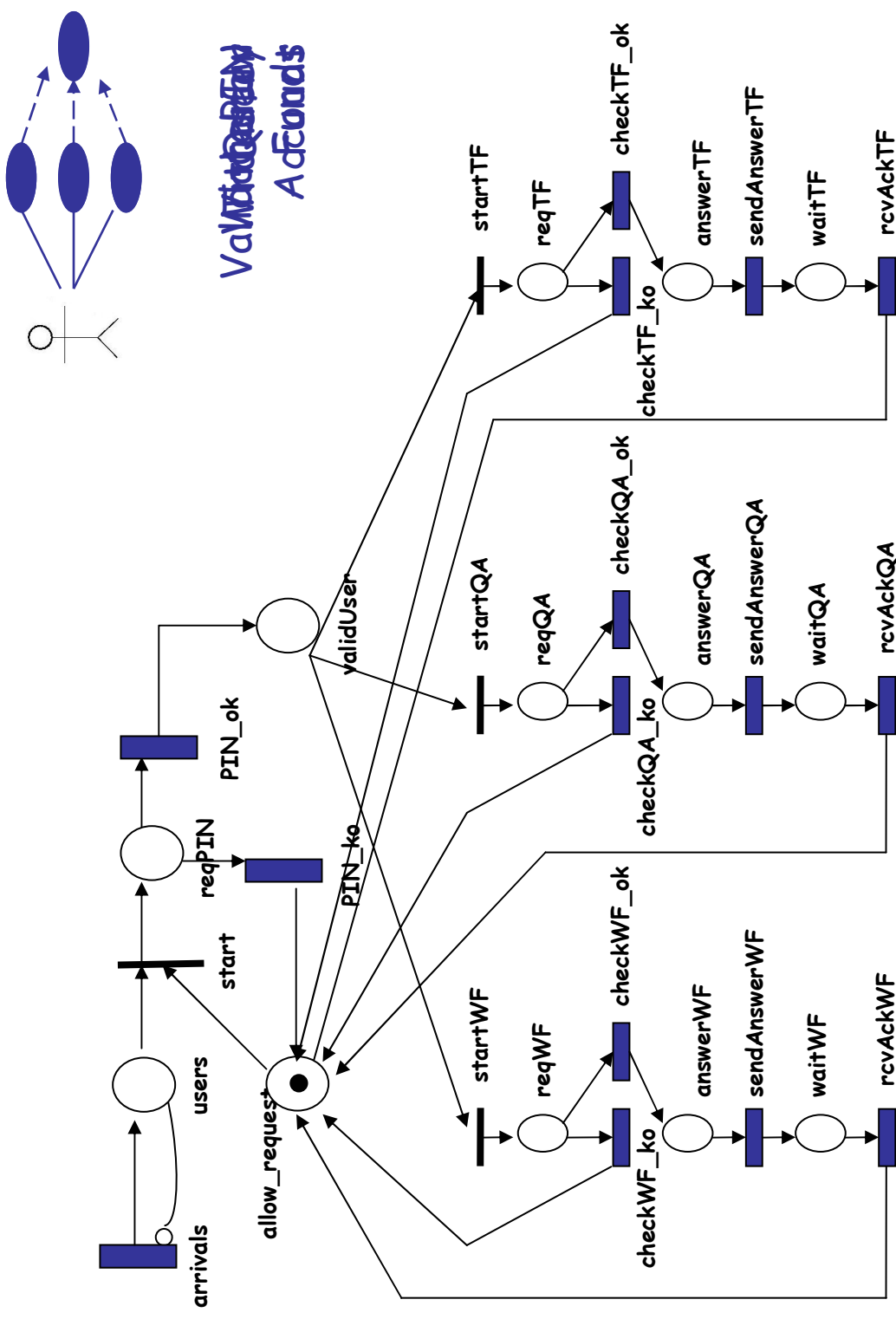
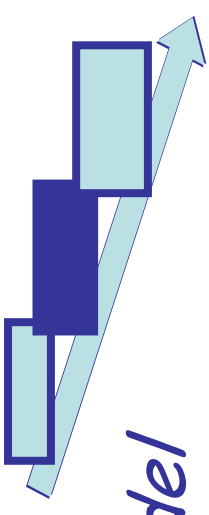
□ Banking System

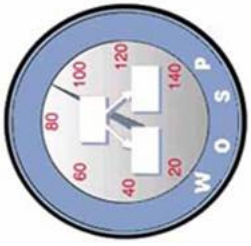




Experimentation:

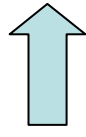
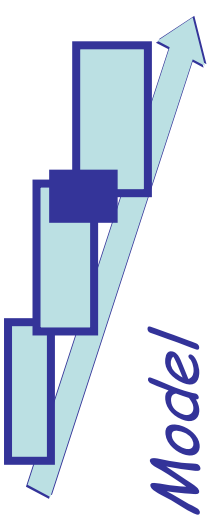
Application Performance Model



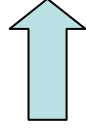


Experimentation: towards a

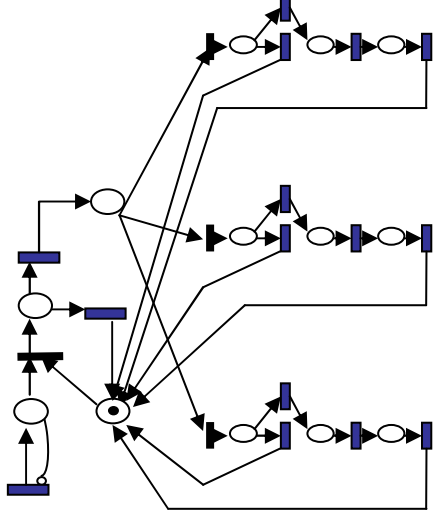
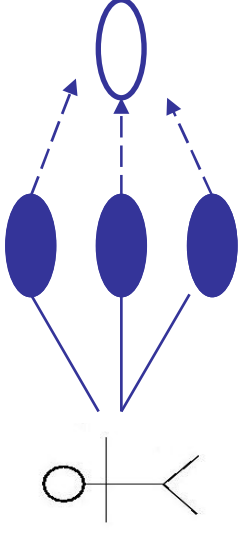
Application Security Performance Model



Application Model

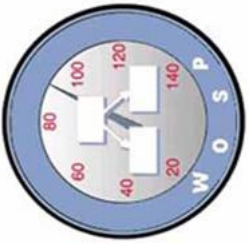


Application Performance Model



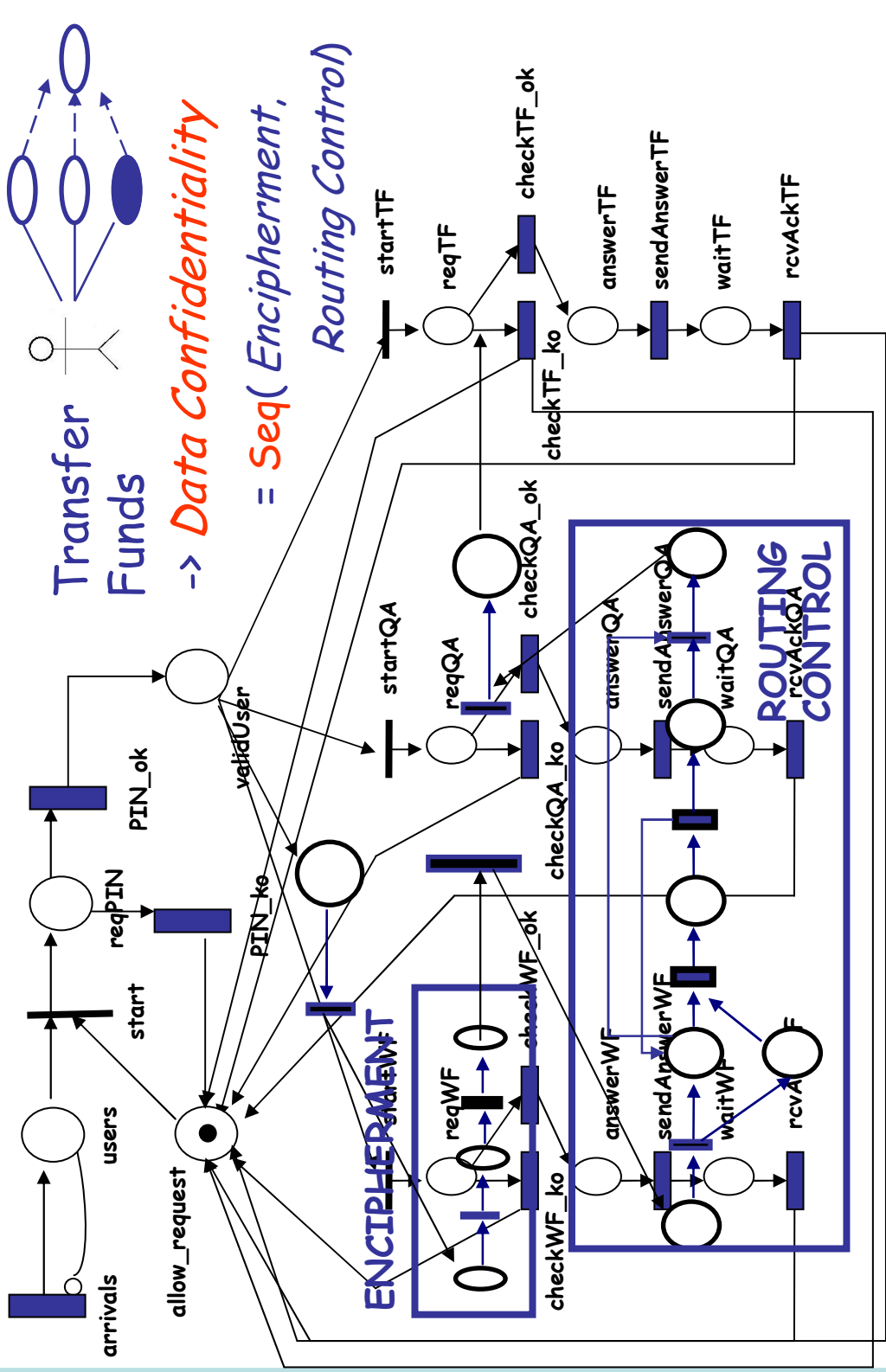
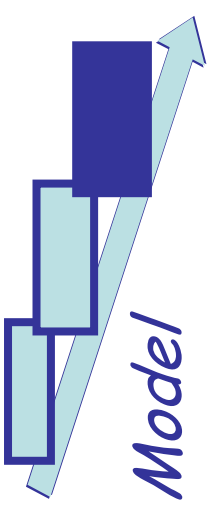
...and which *Security Solutions* ?

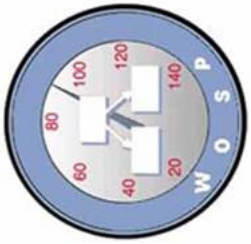
- Withdraw Funds -> *Availability*
- Query Account -> *Access Control*
- Transfer Funds -> *Data Confidentiality*



Experimentation:

Application Security Performance Model



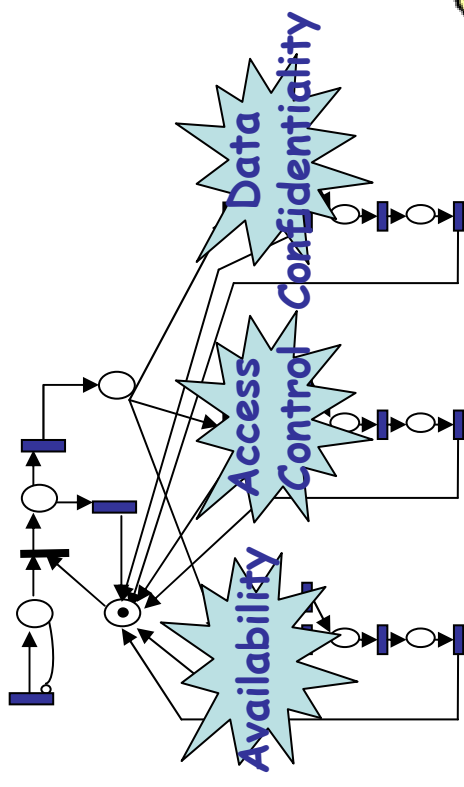
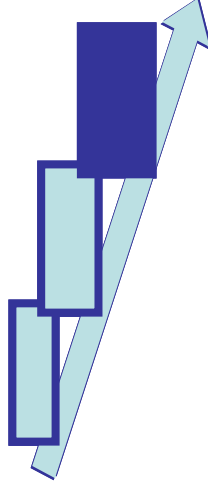


Experimentation

□ Let us compare two configurations:

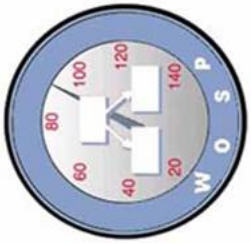
1. Banking System

(i.e. the *Application Performance Model*)



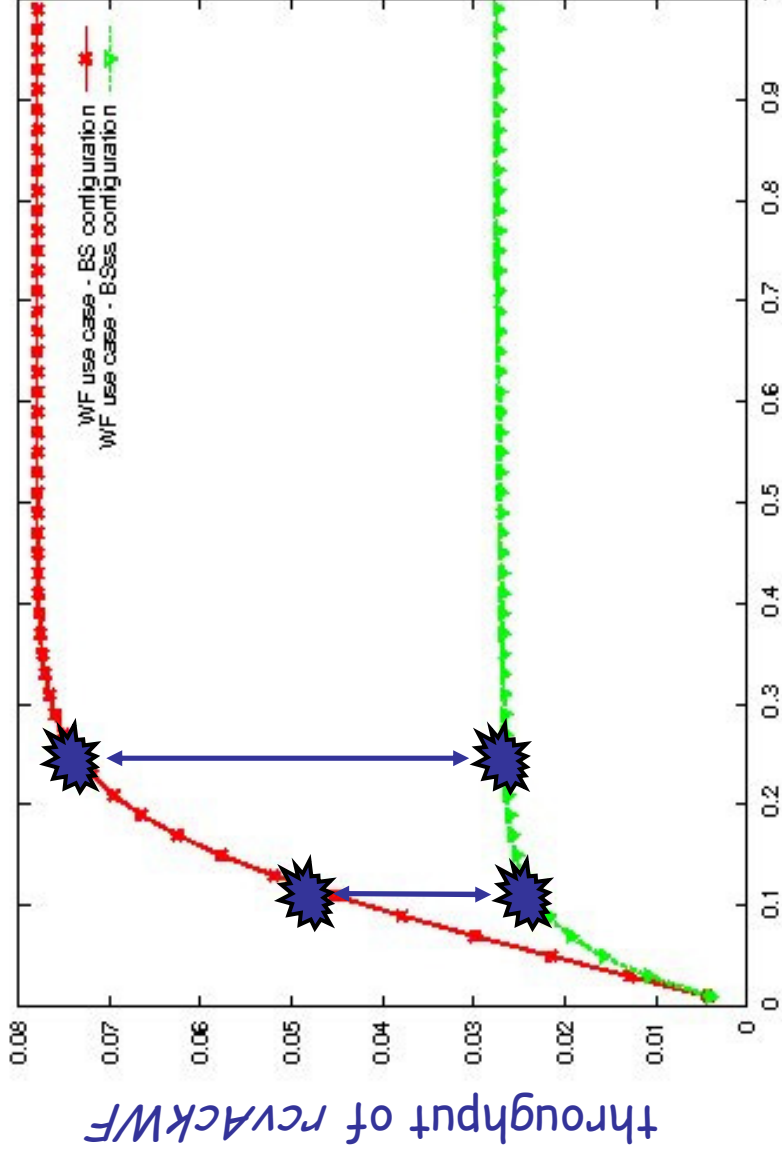
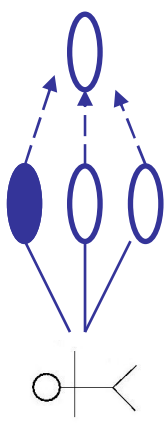
2. Banking System with Security Services

(i.e. the *Application Security Performance Model*)

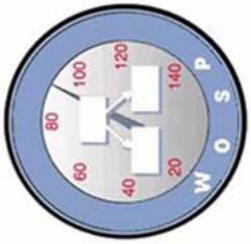


Experimental results

□ Throughput Analysis (in WF use case)

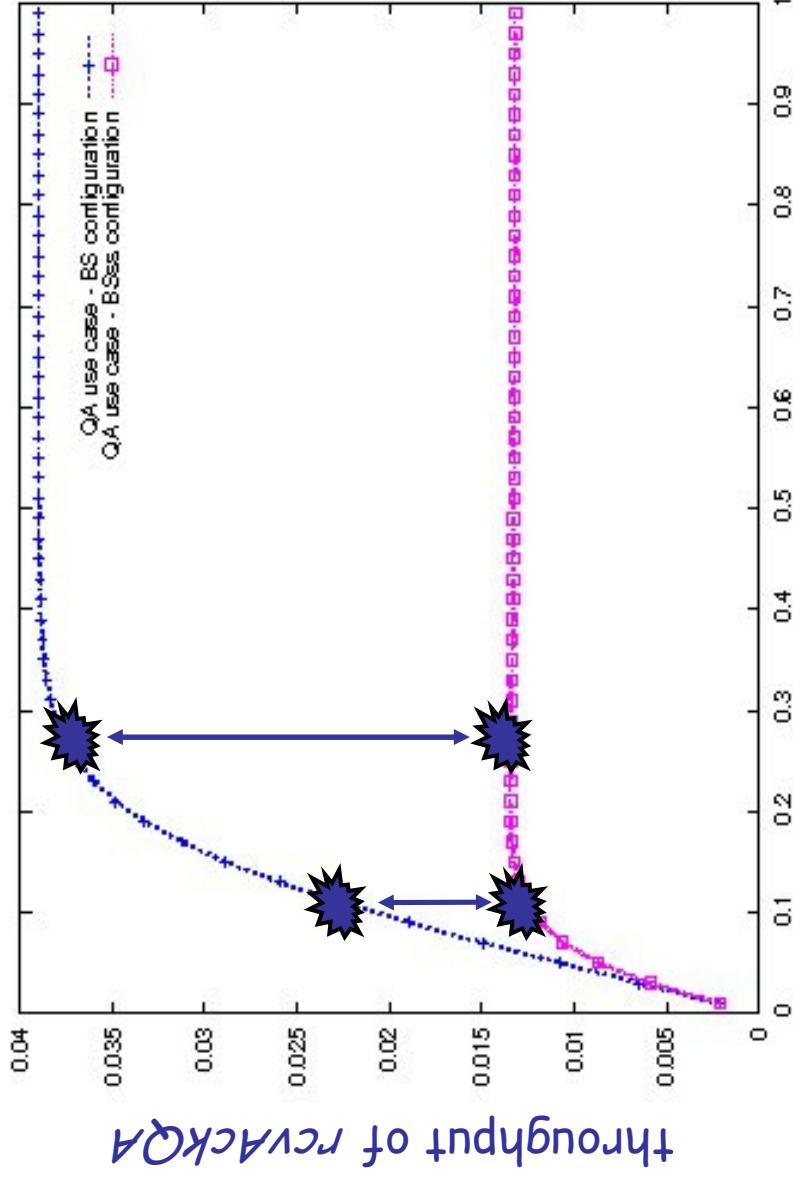
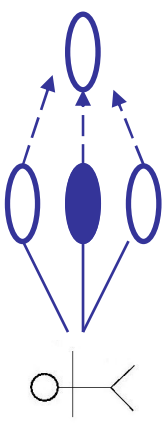


Withdraw
Funds

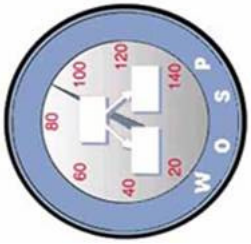


Experimental results

□ Throughput Analysis (in QA use case)

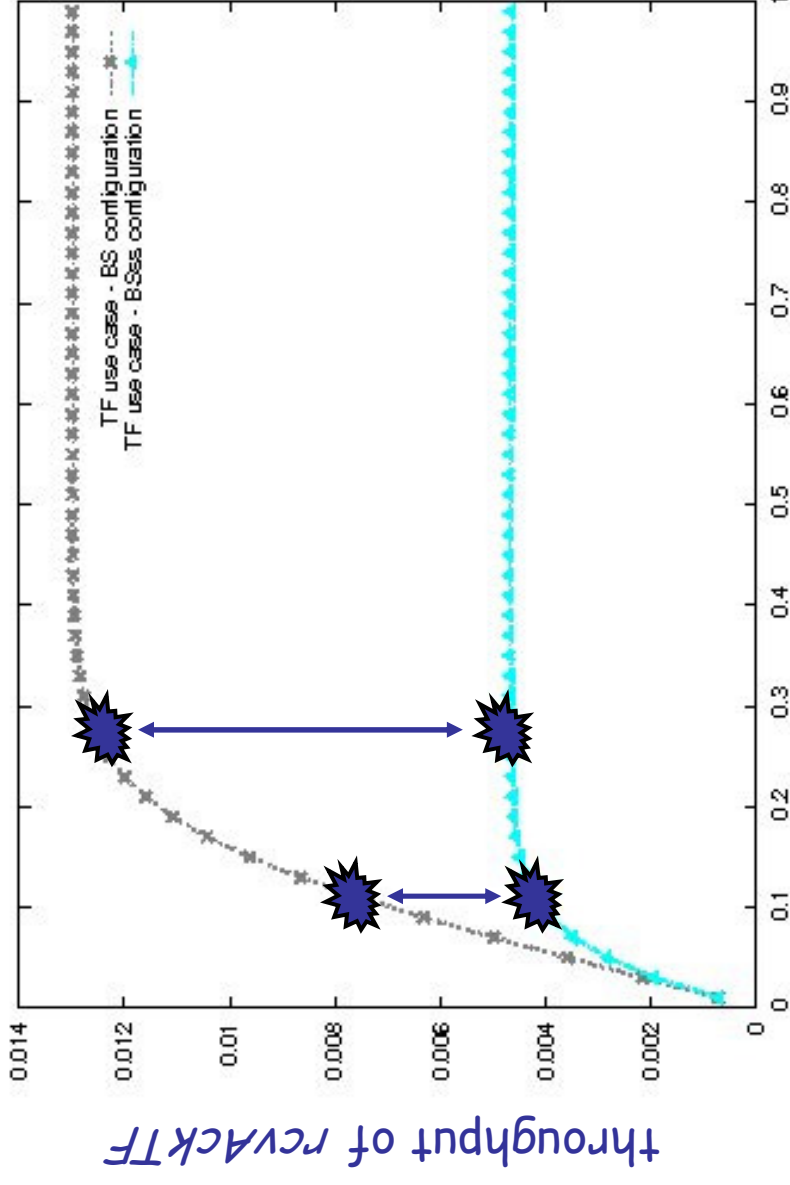
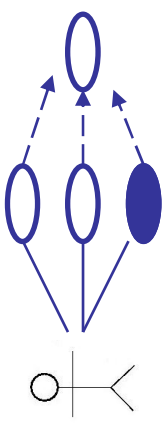


Query
Account

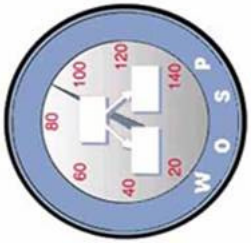


Experimental results

□ Throughput Analysis (in TF use case)

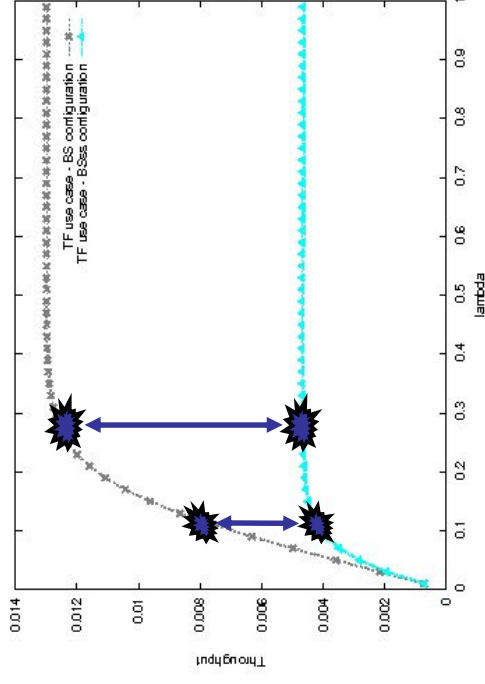
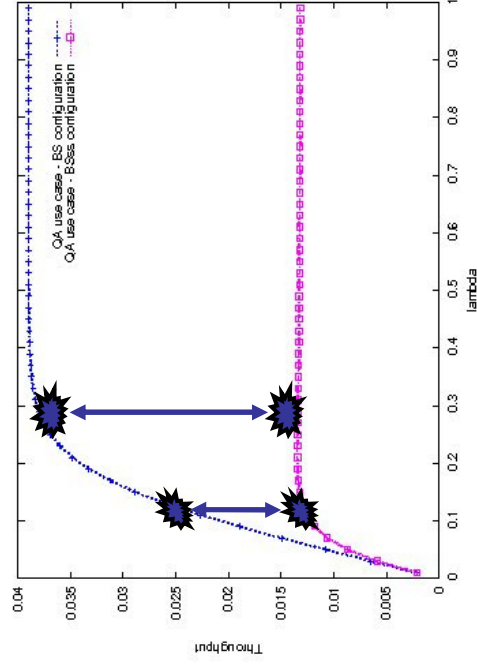
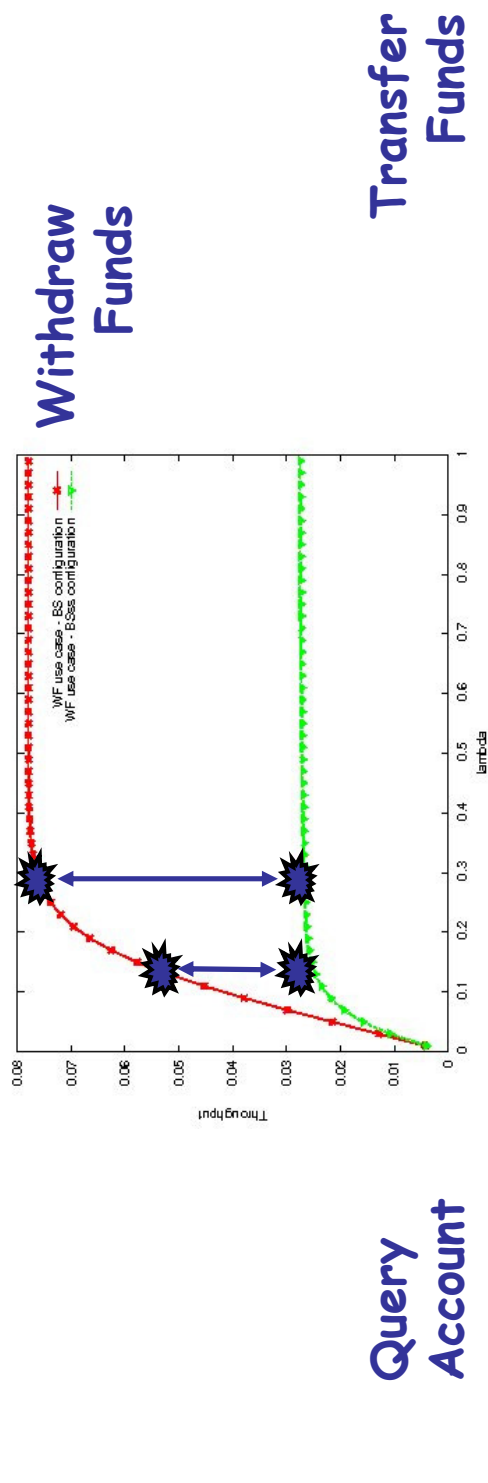


Transfer
Funds



Experimental results

□ Throughput Analysis (in use cases)



SUMMARY

- Non-functional analysis and software development
- Model-driven performance analysis
- Model-driven reliability analysis
- Model-driven tradeoff analysis

- Tool support

- Research perspectives

Our “zoo” of tools

61

<http://sealabtools.di.univaq.it/SeaLab/index.html>

- **MOSQUITO**
MOdel driven conStruction of QUeuIng
neTwOrks
- **COBRA**
COmponent-Based Reliability Analysis
- **DEER**
DEcision support for componEnt-based softwaRe
- **WEASEL**
Web sERvice for Analyzing queueing networks
with multiple solvers

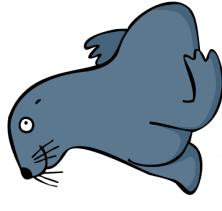


... and other "animals" yet to come

62

- SEAL

Software architecture uml modeling of Aemilia
specification tool



- GARFIEL

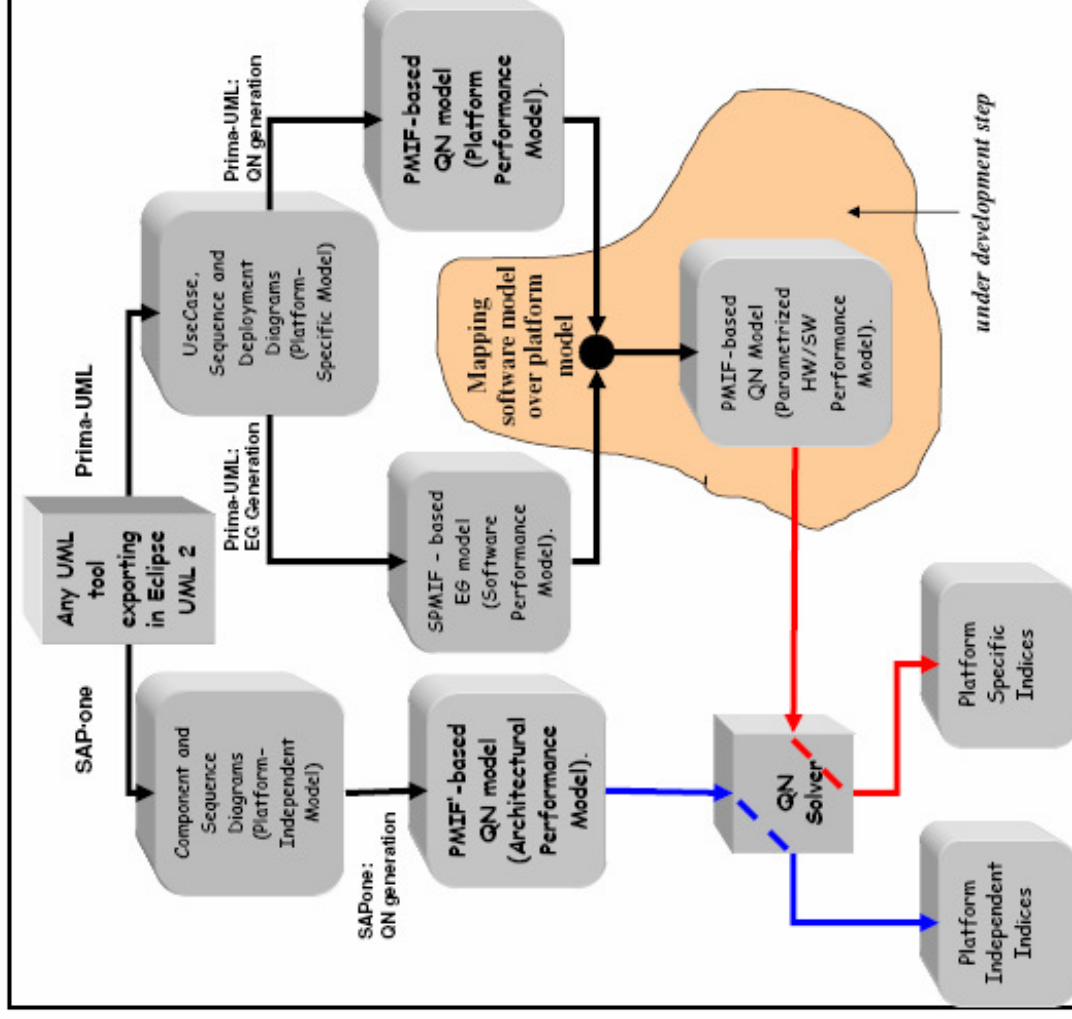
Generation of Architectural Feedback from
analysis of performance results



MOSQUITO

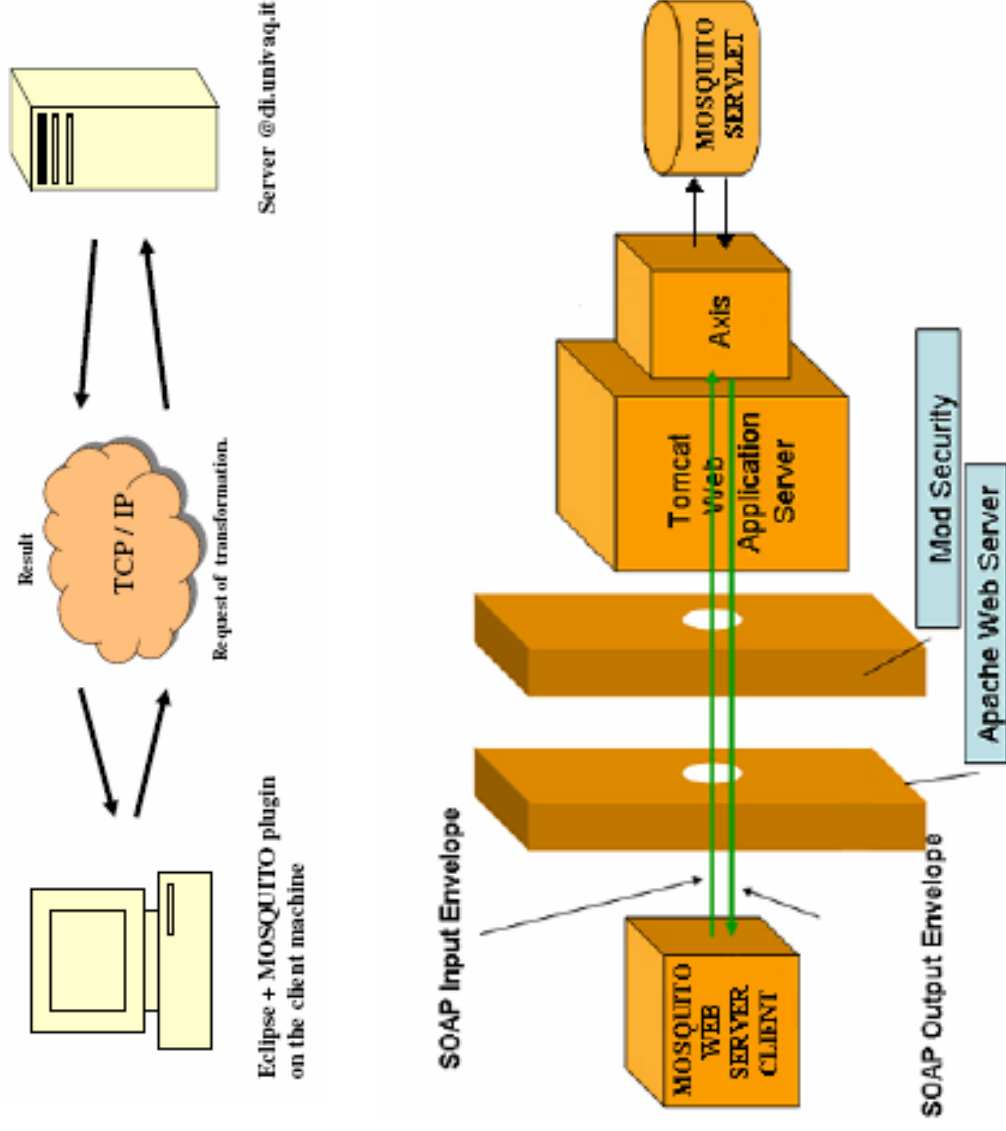
63

MOSQUITO is a tool that generates Queuing Network and Execution Graph models from annotated UML models according to the SAP-one and the Prima-UML methodologies.



MOSQUITO

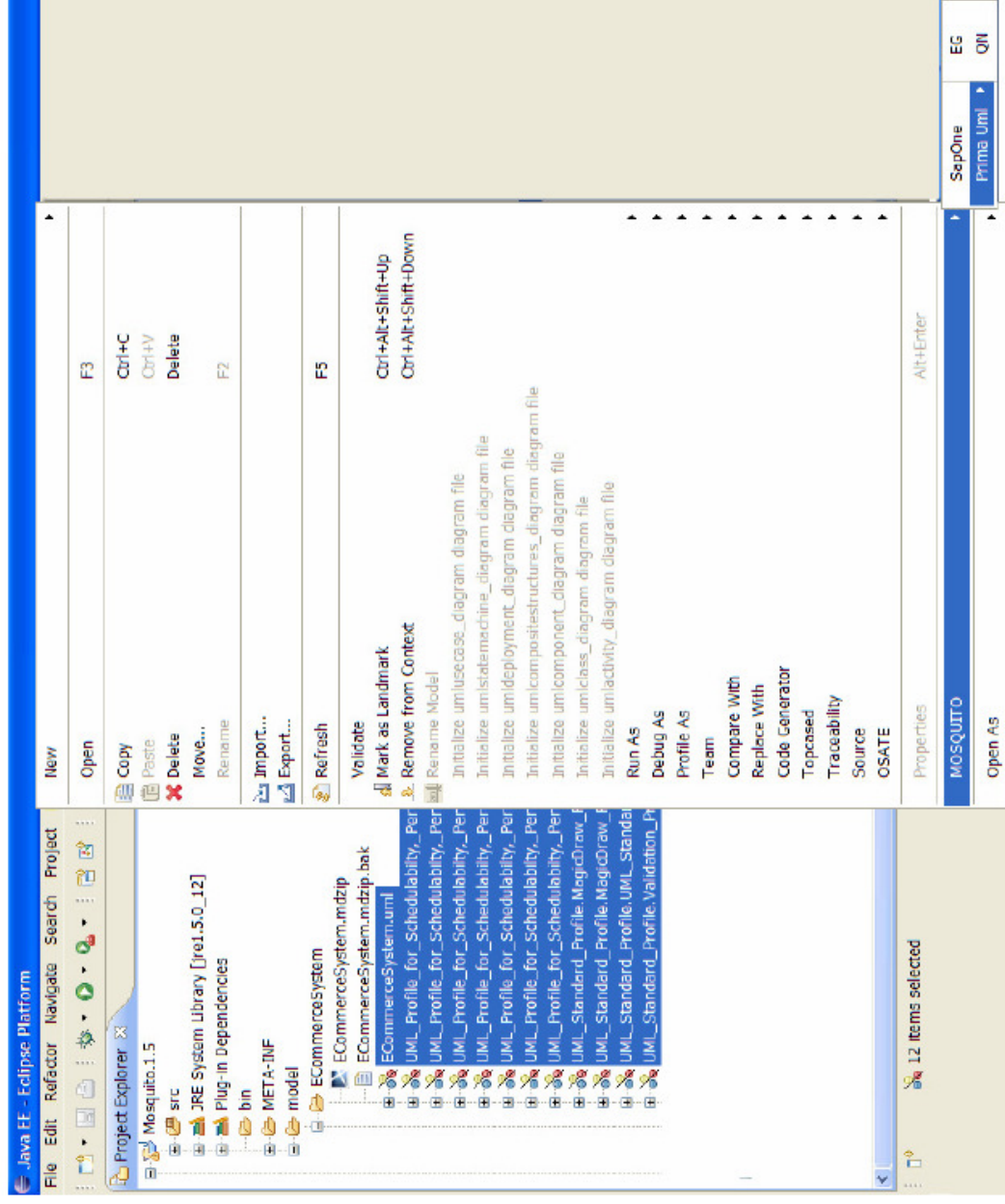
64



MOSQUITO has a client/server architecture. A MOSQUITO downloadable plugin implements the client side that provides the functionality to invoke the web services provided on the server side at University of L'Aquila.

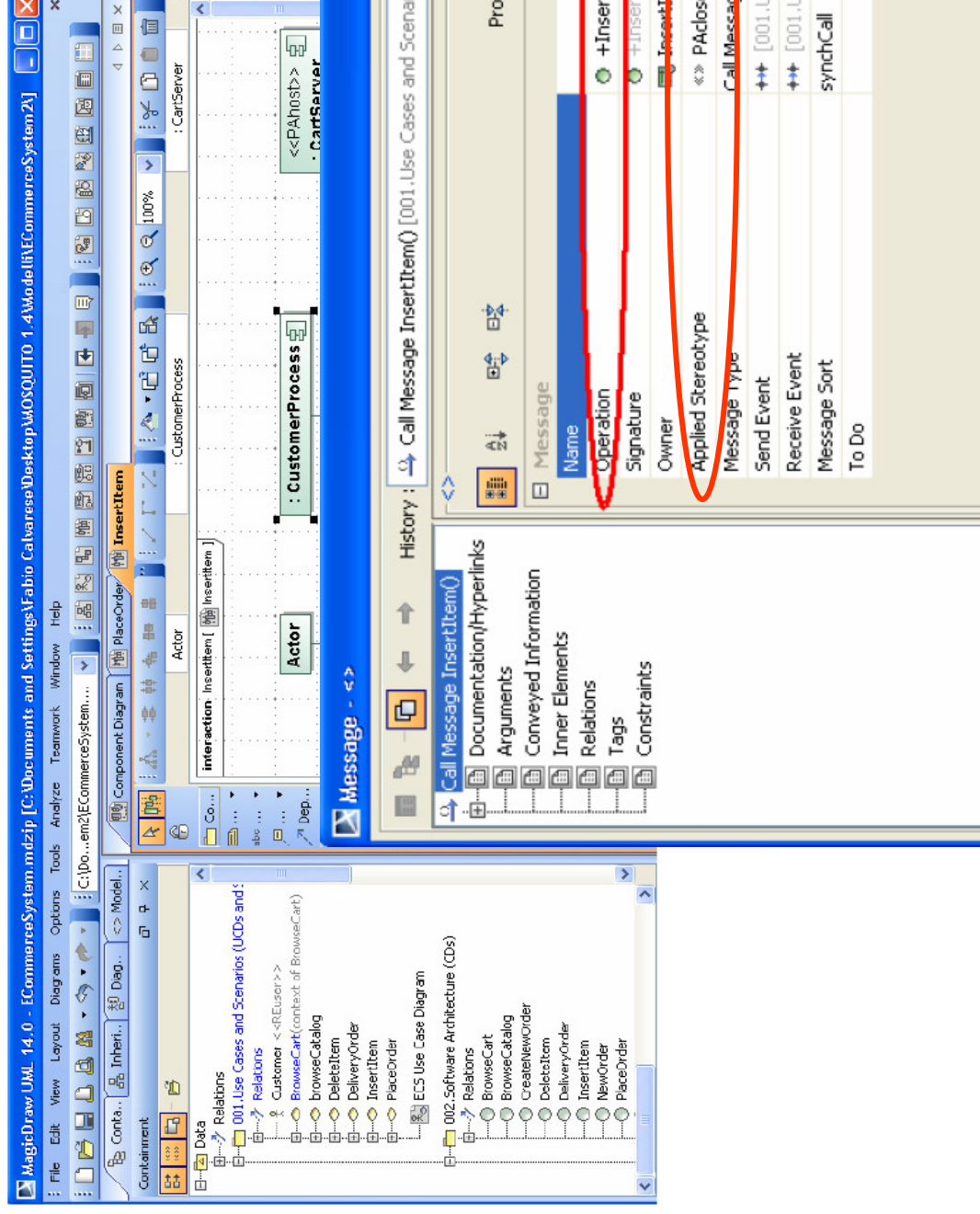
MOSQUITO

65

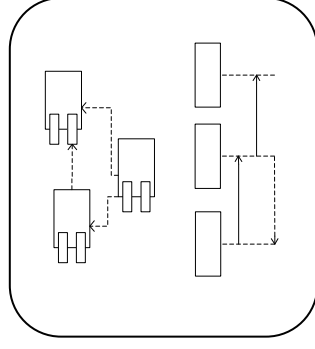


The extension point used for MOSQUITO interface is the Eclipse popup menu. After the creation of a model the user must only select the UML files (*.uml) and activate the desired transformation

Annotation example in MagicDraw

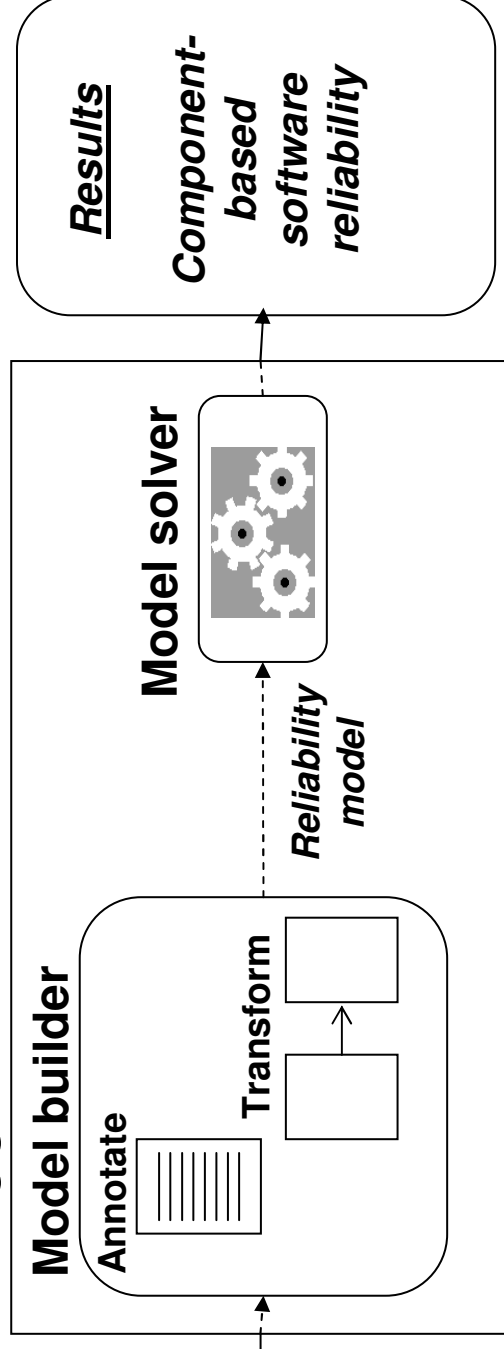


Visual Paradigm



**Software model
(Component Diagram)**

COBRA



COBRA is a tool that generates (and solves) reliability models for component-based software from annotated UML models

The most recent reliability model we had as a target:

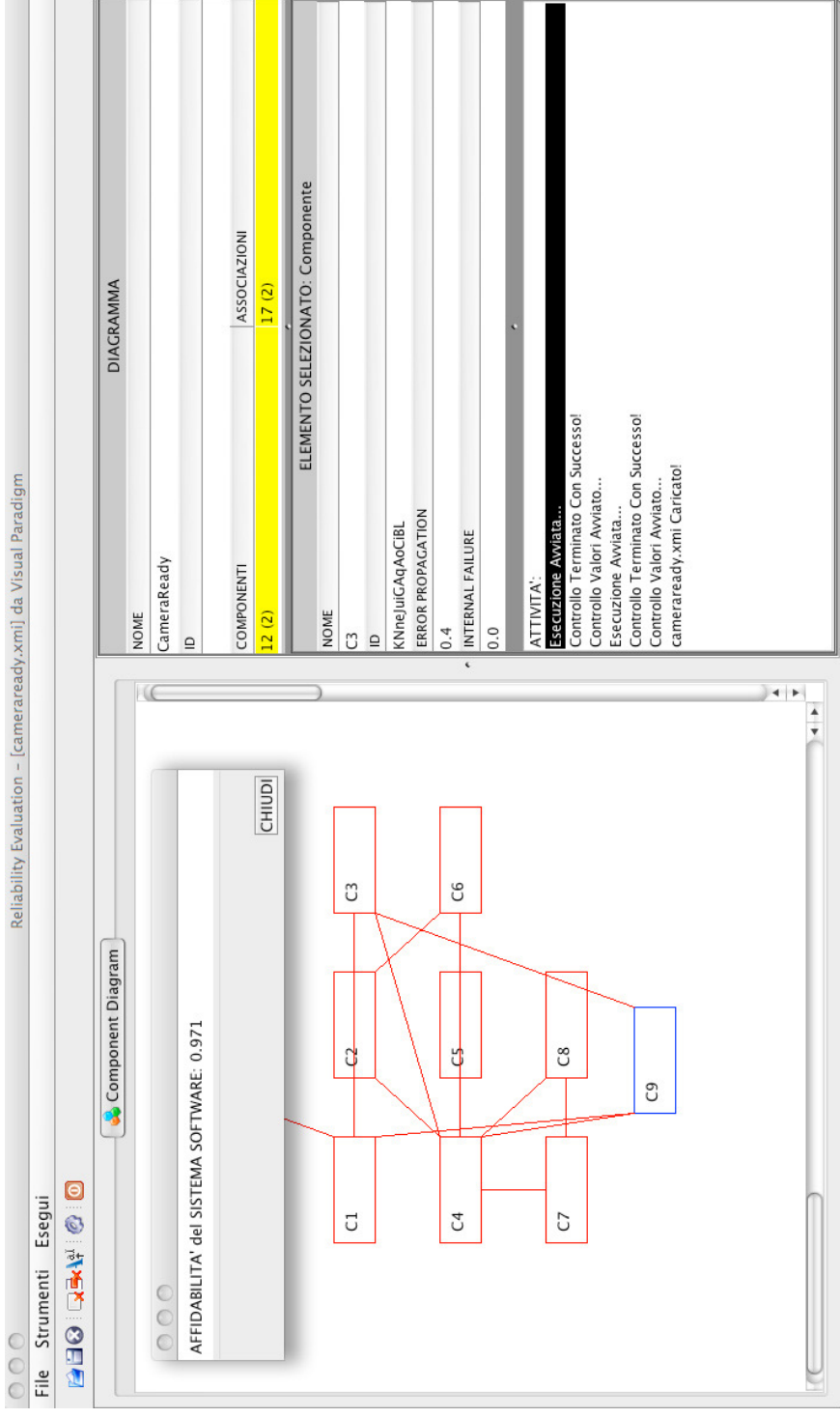
- is based on failure probability of software components
- includes error propagation
- does not consider connector and platform failures

$err^{(k)}(i, j)$: probability that the application reaches comp. j after k control transfers, starting from comp. i , and j produces an erroneous output

$$err^{(k)}(i, j) = p^{(k)}(i, j) \cdot if(j) + ep(j) \cdot (1 - if(j)) \sum_{h=0}^C err^{(k-1)}(i, h) p(h, j)$$

$\mathbf{e}$: vector of the probabilities that the application (for each possible initial component) produces an erroneous output

$$\mathbf{e} = (\mathbf{I} - \mathbf{Q})^{-1} \cdot \mathbf{F} \cdot (\mathbf{I} - \mathbf{Q} \cdot \mathbf{R} \cdot (\mathbf{I} - \mathbf{F}))^{-1} \cdot \mathbf{c}$$

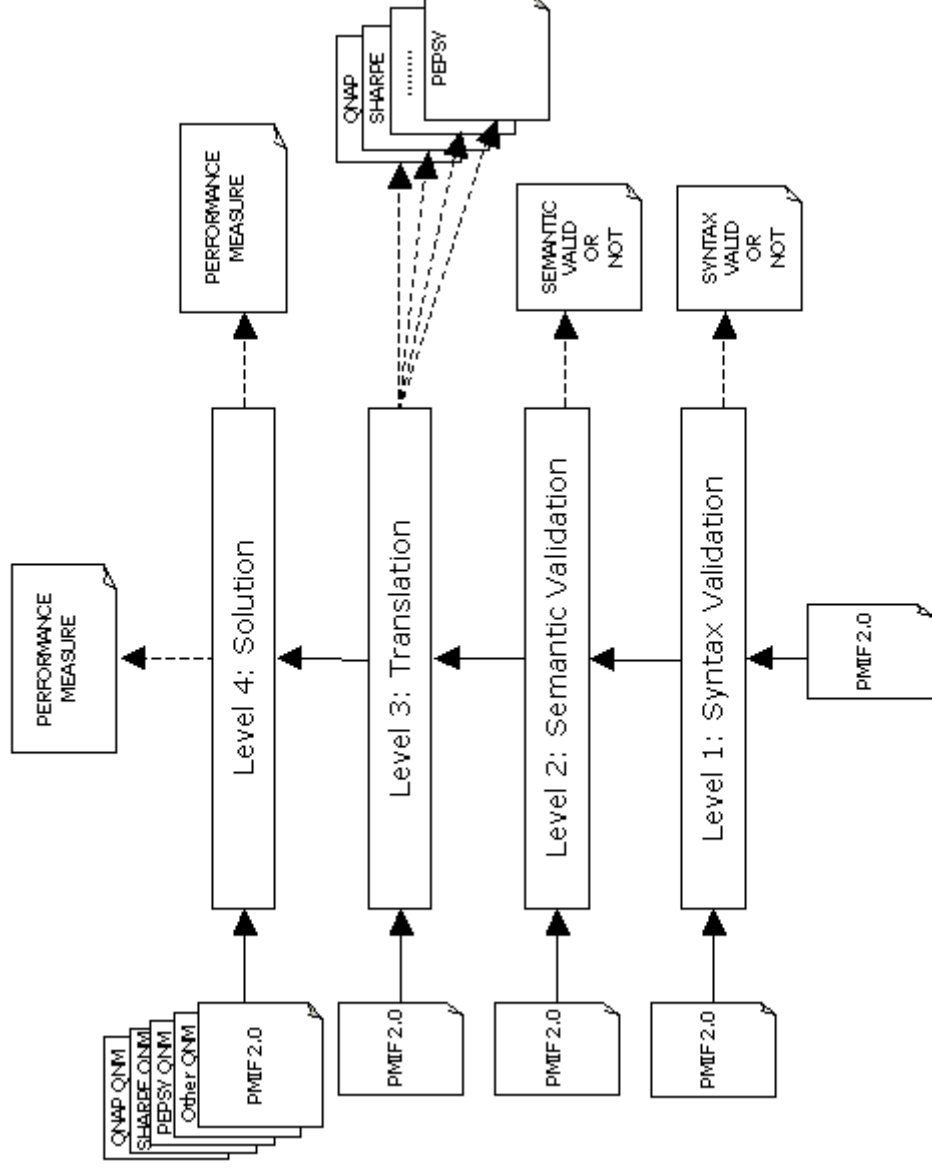


COBRA is an Eclipse plugin and provides a GUI to annotate UML models (at the moment imported from Visual Paradigm) and invoke the reliability model solution

DEER is a tool embedding (3 types of) transformations from UML and non-UML models to optimization models for supporting software component selection

WEASEL

71



WEASEL basically offers a Web Service that allows to solve Queueing Network models, specified in PMIF format, by invoking multiple external solution tools

- Up to now WEASEL provides input to the following solvers: QNAP, SHARPE, PDQ, PEPsy, MQNA1/MQNA2, PMVA, MVA-QFP, OPENQN/CLOSEDQN.
- Its architecture is open to easily add the capability to interact with other solvers. WEASEL is fully customizable and extensible, as users can add new tools and capabilities.
- WEASEL follows a simple client-server approach to accomplish this scope, based on the web service standard SOAP protocol and WSDL specification language.

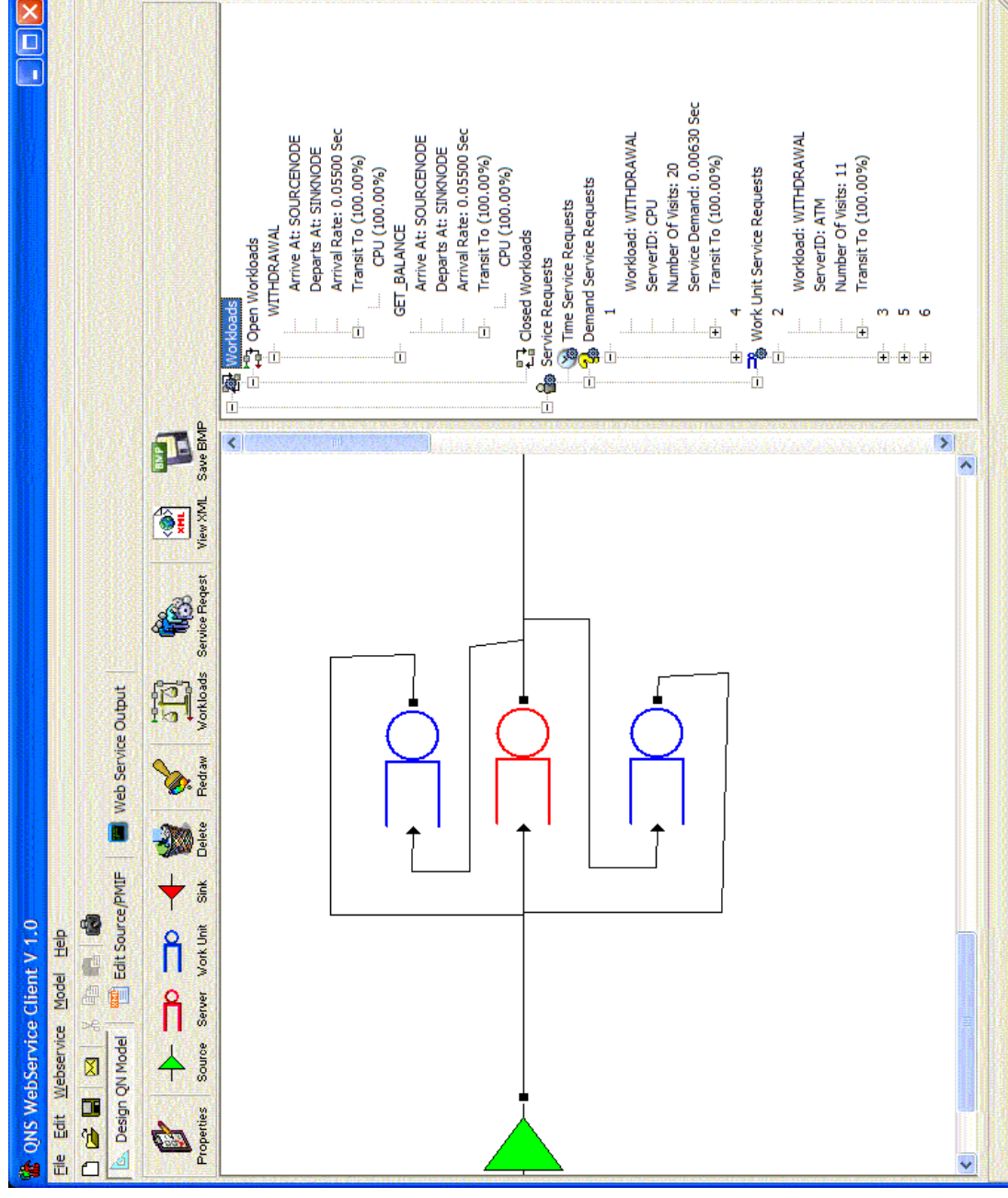
End users can develop their own web clients and implement them with any programming language that provides SOAP support.

Currently available WEASEL clients

- PHP-based command line interface
- AJAX (Asynchronous Javascript And Xml) - based web interface
- Delphi-based Windows application (PMIF Editor)



PMIF Editor screenshot



SUMMARY

- Non-functional analysis and software development
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- Tool support

• Research perspectives

- Non-functional attributes may be (strictly) correlated, so sophisticated models to capture dependencies are needed
- Conflicts between non-functional and functional analysis results
- Automated interpretation of analysis results and feedback generation
- Keeping aligned software models and analysis models (in both directions)
- Introducing an unified representation of non-functional attributes to favor tool interoperability
- Role of pivot languages in all previous problems

A new direction:

Model synchronization and differences

